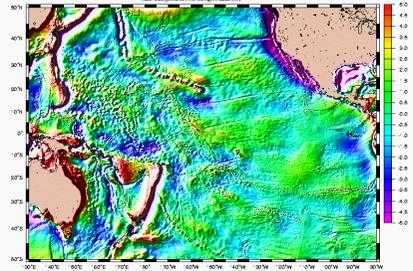




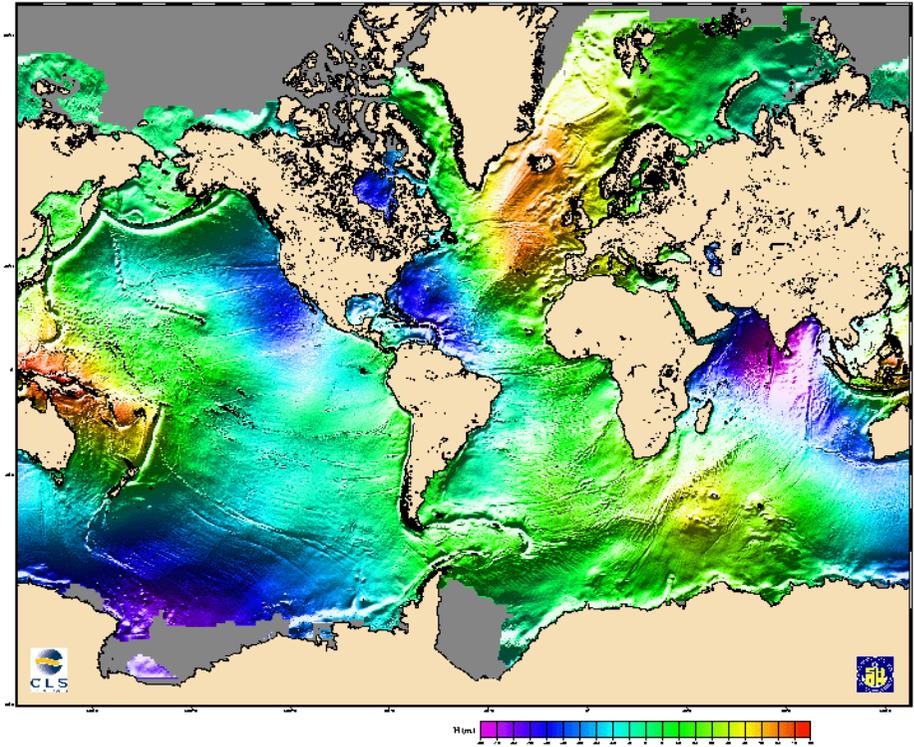
Mean Sea Surface Dedicated to Ocean Studies

ABSTRACT

Topex/Poseidon (T/P), GEOSAT, and ERS-1 improved altimetric dataset are used to estimate a mean sea surface (MSS). This MSS is dedicated to oceanography, focusing on the accuracy of the mean sea height along the satellite ground tracks. The 3-years T/P accurate (1.2 cm rms) mean profile is processed to reference the MSS. A two-year ERS-1 mean profile is calculated by merging phase C and G datasets, with a 1.6 cm rms accuracy. The two-year GEOSAT mean profile is 2 cm rms accurate. These two profiles are adjusted to T/P. The data of the two 168-day ERS-1 geoid cycles are also used, to provide a global high resolution to the MSS. For all the ERS-1 data, the ocean variability is removed from the sea surface height by subtracting the T/P sea level anomaly (SLA), then the orbit error is also reduced by spline-fitting with T/P arcs, allowing a 6.5 cm rms accuracy. EGM96 geoid is removed to the data. A suboptimal inverse technique is applied to estimate the MSS from these residuals, on a 1/16° grid. This technique takes into account the long wavelength biases on altimetric arcs and also the oceanic variability noise. The MSS is validated first by analyzing discrepancies with the mean profiles : e.g., less than 1.3 cm rms and 0.11 cm/rms with the T/P mean profile in a global evaluation. Its accuracy is improved compared to other MSS, particularly at small scales. And there are about 3.6 and 5.1 cm rms discrepancies with OSU95 MSS and the GRGS MSS respectively. The second validation is based on difference between the three MSS, and the standard deviation is below 11 cm. A final test show that to use the MSS to reference altimetric Sea Level Anomalies (SLA) is valuable: it allows a merging of several satellite data set reducing systematic biases.



Mean Sea Surface CLS_SHOM



OBJECTIVE

- The MSS must be accurate along and close to the satellite track pattern (e.g., T/P, ERS-1, GEOSAT, JASON, ENVISAT)
- The MSS must contain the short wavelength of the geoid undulations at the vicinity of the satellite ground tracks.

The MSS should be the reference for calculating and merging homogeneously Sea Level Anomalies from different satellites.

DATA

Three-year T/P mean profile
Cycles 1 to 101 (January 1992 to December 1994), NASA/GSFC data.

Two-year ERS-1 mean profile
Merged cycles C and G (1992-1995), cycle 101 to 102 (Jan 95 to Sep 95) to get two years of data with an 80°E-80°W coverage.

Two-year GEOSAT mean profile
Cycles 1 to 40 (January 1992 to December 1993), NASA/GSFC data.

PREPROCESSING & PROCESSING

	Mean profile T/P	Mean profile ERS-1	Mean profile GEOSAT	ERS-1 geoid cycle
length	101994-05	10111-10111	10111-10111	10101-10101
resolution in the track	15 km	15 km	15 km	15 km
coverage	60°E-60°W	60°E-60°W	60°E-60°W	60°E-60°W
accuracy	1.2 cm	1.6 cm	2 cm	6.5 cm
particularity	reference for all altimetric observations	adjustment of T/P cross-track differences (covariance method), adjustment in T/P arcs	adjustment of T/P cross-track differences (covariance method), adjustment in T/P arcs	reference for the geoid undulations
RMS of observed differences between profiles	1.6 cm	1.7 cm	6.5 cm	11.3 cm
internal accuracy	1.2 cm	1.6 cm	2 cm	6.5 cm
reference difference from T/P	1.2 cm	2 cm	1.2 cm	6.5 cm
reference difference from ERS-1	4.8 cm	3.2 cm	10 cm	-

GRIDGING or ESTIMATION METHOD

Inverse method, taking into account large scale errors along the satellite tracks (A. Traou et al., 1997)

OBSERVATIONS:

- Positions of the Mean Heights in the EGM96 geoid
- Data noise
- Measurement errors
- Large scale errors (e.g. residual orbit error)
- Particularity of oceanic variability

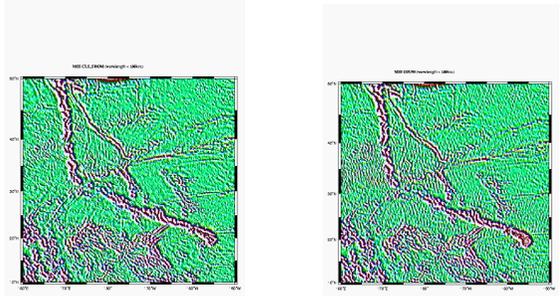
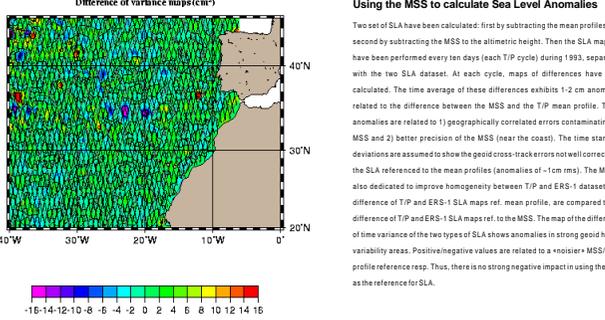
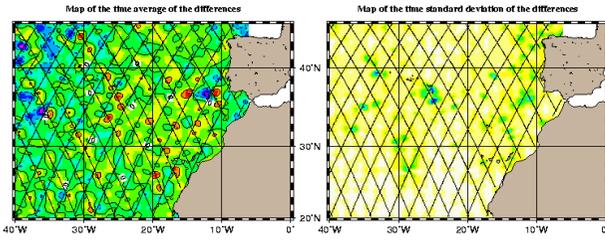
METHOD:

- For each grid point in the final calculation grid (0.25° x 0.25°):
- Data are collected in the 200 km radius reference radius
- The mean is calculated and subtracted, to cover the observations
- The observation covariance matrix is inverted
- A regular estimator (T/P x 1/16°) is processed, using the covariance matrix, providing estimated sea surface
- The final mean and the EGM96 sea surface are added back to the estimates.

Mean Sea Surface Determination

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    graph TD
      A[Data: T/P, ERS-1, GEOSAT] --> B[Preprocessing: Environmental & Instrumental corrections]
      B --> C[Data processing: Calculation of Mean Height Measurements]
      C --> D[Averaging: Mean profile processing for T/P, ERS-1 (3-yr), GEOSAT]
      C --> E[Ocean Variability Reduction: The ocean variability is removed by T/P SLA]
      C --> F[Crossover Analysis: Reduction of orbital errors adjusted to T/P]
      D --> G[Gridding: Inverse Method applied to MSS determination]
      E --> G
      F --> G
      G --> H[Validation: Comparison between MSS and CLS]
      H --> I[Validation: In order to validate and improve the MSS calculation, several tests are scheduled: 1. Look at the differences between the T/P, ERS-1 and GEOSAT mean profiles and corresponding interpolated values of the MSS. 2. Compare the grid dimensions with the short cycle mean profile to verify the resolution of the profile wavelengths of the geoid. 3. Comparisons with MSS: MSS calculated with the GEOSAT Geoid Anomalies, in particular the OSU95 MSS (V. 1995) and the GRGS MSS (Mazzotta et al., 1996).]
      I --> J[Error of the Mean Sea Surface CLS_SHOM]
      J --> K[Difference of variance maps (cm²)]
      K --> L[Using the MSS to calculate Sea Level Anomalies]
      L --> M[CONCLUSION]
      M --> N[PERSPECTIVE]
      
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Using the MSS to calculate Sea Level Anomalies

Two sets of SLA have been calculated: first by subtracting the mean profiles, and second by subtracting the MSS to the altimetric height. Then the SLA mapping have been performed every ten days (each T/P cycle) during 1993, separately with the two SLA dataset. At each cycle, maps of differences have been calculated. The time average of these differences exhibits 1-2 cm anomalies related to the difference between the MSS and the T/P mean profiles. These anomalies are related to 1) geographically correlated errors contaminating the MSS and 2) better precision of the MSS (near the coast). The time standard deviations are assumed to show the geoid cross-track errors not well corrected in the SLA referenced to the mean profiles (anomalies of ~1 cm rms). The MSS is also dedicated to improve homogeneity between T/P and ERS-1 dataset. The difference of T/P and ERS-1 SLA maps ref. mean profile, are compared to the difference of T/P and ERS-1 SLA maps ref. to the MSS. The map of the difference of time variance of the two types of SLA shows anomalies in strong geoid height variability areas. Positive/negative values are related to a 'noisy' MSS/mean profile reference resp. Thus, there is no strong negative impact in using the MSS as the reference for SLA.

CONCLUSION

- The precision along the mean profiles is kepted (e.g.: 1.3, 2.1, 4.1 cm RMS with T/P, ERS-1, and GEOSAT profiles respectively) and comparable with the crossover differences (e.g.: 1.6, 2.5, 3.7 cm RMS).
- A sensitivity study of the error show that errors are coherent with mean profile discrepancies.
- The mapping of the differences between the 3 MSS show that the CLS_SHOM MSS is not degraded by a trackiness (data noise).
- Compared to other MSS the CLS_SHOM estimates MSS showing better resolution of the short wavelength along the mean profiles.
- Comparisons between SLA calculated with MSS and with mean profiles show that the use of the MSS would pollute the SLA mapping by only 1-2 cm RMS at short scales.

PERSPECTIVE

- The CLS_SHOM MSS will be used for merging present altimeter data and futur data of Jason1, ENVISAT, and GFO.
- The MSS corresponds to the mean oceanic level from 1993 to 1995. The MSS should be determined over a longer period by a reference to 5 year T/P mean profile.
- Our processing and gridding method may be adapted for gravity anomaly and vertical deflection calculations.