Validation of Jason and Topex Microwave Radiometer Wet Path Delay Measurements Using GPS, SSM/I, and TMI Shailen Desai, Bruce Haines, Wenwen Lu, and Victor Zlotnicki Jet Propulsion Laboratory, California Institute of Technology, Pasadena, California, U.S.A.

Abstract

Recalibration of the Jason and Topex Microwave Radiometers (JMR and TMR) has been performed over the last year by S. Brown et al. The recalibrated JMR and TMR wet path delay measurements are validated through comparisons to respective measurements from terrestrial Global Positioning System sites, the Special Sensor Microwave Imager onboard the Defense Meteorological Satellite Program satellites, and the Tropical Rainfall Measuring Mission's Microwave Imager. Intercomparisons of the TMR and JMR data during the tandem phase and collinear phases are also performed. From these various comparisons we provide estimates of any remaining errors in the recalibrated data such as scale errors, geographically correlated errors, and temporal errors such as drift or yaw state effects.

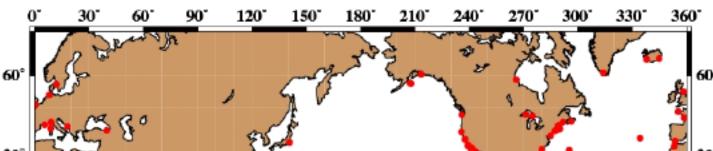
Independent Wet Path Delay Measurements

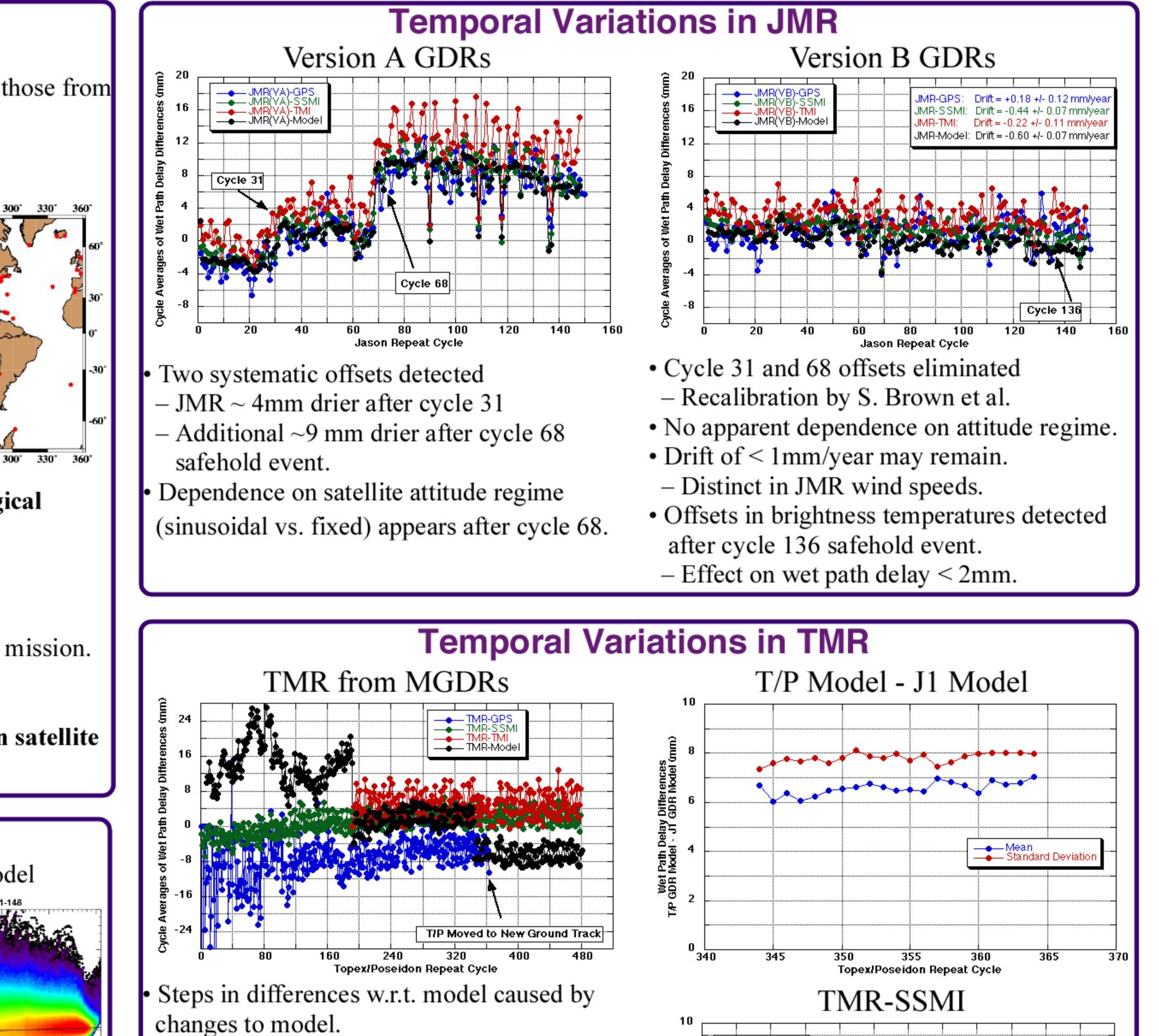
Four independent measurements of wet path delay are used to validate those from the Topex and Jason Microwave Radiometers (TMR and JMR): • ECMWF Model

- Adopt model as provided on the respective GDRs.

Coastal Global Positioning System Sites

- 1-87 sites per cycle available for Topex/Poseidon mission. – Only use TMR-GPS when T/P on original ground track. – 87 sites per cycle available for duration of Jason-1 mission. – Some sites have more than one nearby overflight. • Special Sensor Microwave Imager (SSMI) on Defense Meteorological Satellite Program (DMSP)



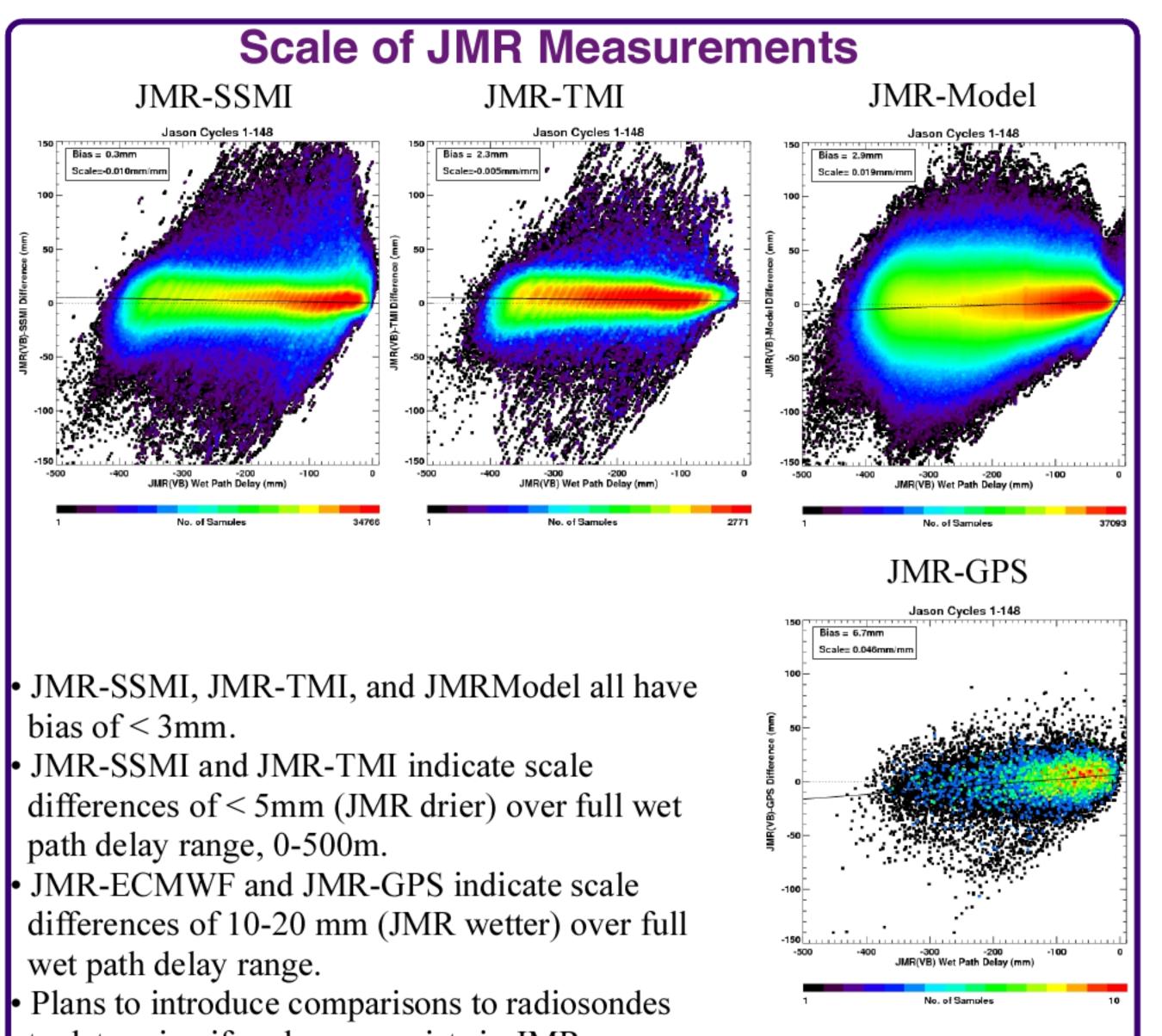


Available for duration of Topex/Poseidon and Jason-1 mission. •Tropical Rainfall Measuring Mission's Microwave Imager (TMI) Launched November 1997.

Available from Topex/Poseidon cycle 193 and for duration of Jason-1 mission.

TMR data used in this study are as provided on the MGDRs.

• No corrections are applied for the known drift and dependence on satellite attitude regime.

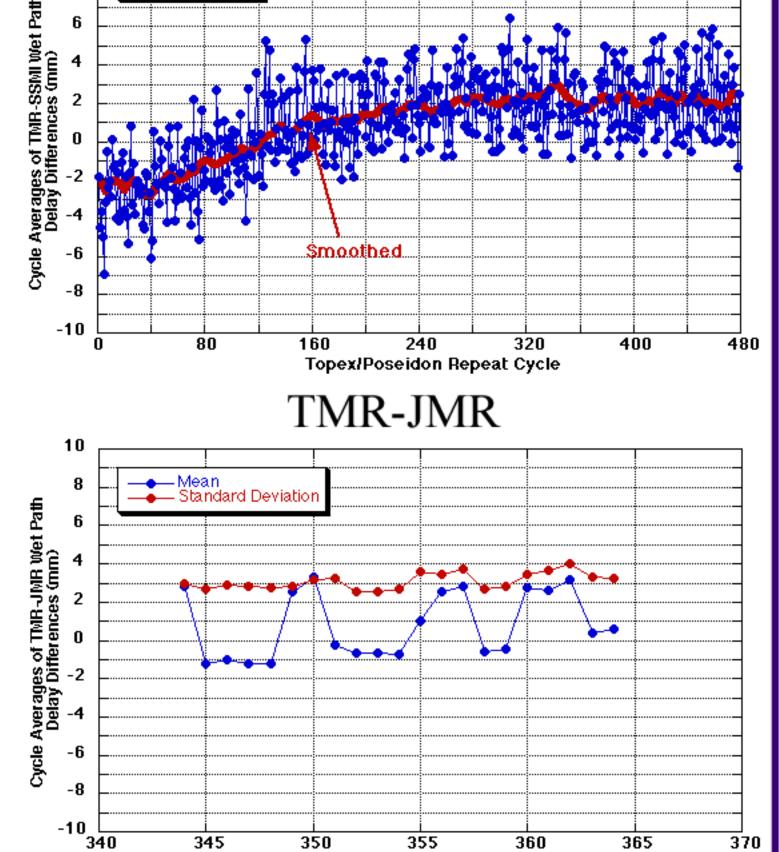


- to determine if scale error exists in JMR.

TMR-Model biased -8.2 mm w.r.t. TMR-SSMI after cycle 344.

– In contrast, JMR-Model is biased -1.2 mm w.r.t. JMR-SSMI during same period. – Caused by bias between models provided on T/P and J1 GDRs of 6.6 mm (T/P drier). TMR drift of 0.7-0.9 mm/year to ~cycle 280 clear in TMR-SSMI.

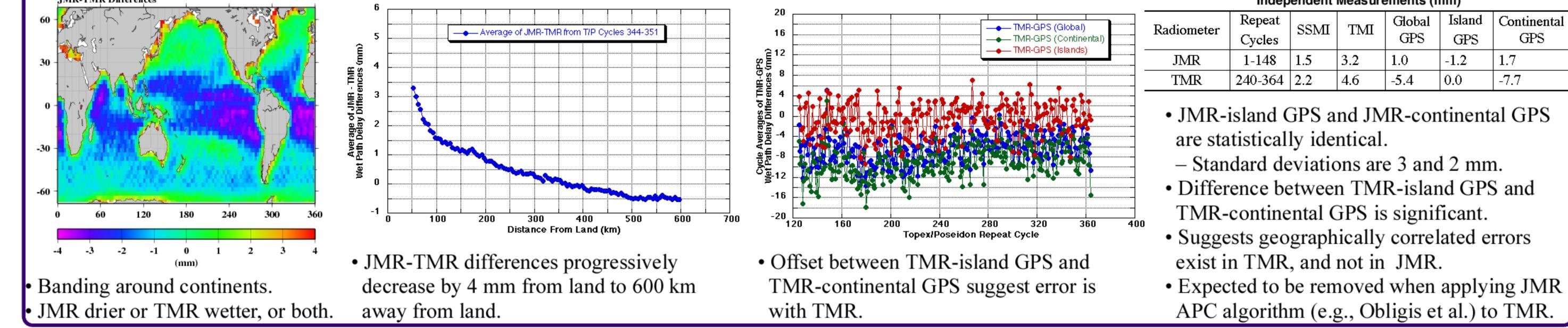
- Known cause is drift in all 3 brightness temperatures, primarily 18 GHz channel. Dependence on satellite attitude regime clear in all four differences.
- $-\sim 4$ mm peak to peak.
- TMR-JMR has mean of $\sim 1 \text{ mm}$, and standard deviation of 3-4 mm.
- TMR-GPS biased by ~-8 mm with respect to TMR-SSMI
- Inconsistent with JMR-GPS vs. JMR-SSMI during same period where bias is < 1mm.



— TMR-SSM

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Average of JMR-TMR from T/P Cycles 344-351



Geographically Correlated Errors in JMR or TMR

Average of Differences Between Radiometer and Independent Measurements (mm)

Topex/Poseidon Repeat Cycle

Radiometer	Repeat Cycles	SSMI	TMI	Global GPS	Island GPS	Continental GPS
JMR	1-148	1.5	3.2	1.0	-1.2	1.7
TMR	240-364	2.2	4.6	-5.4	0.0	-7.7