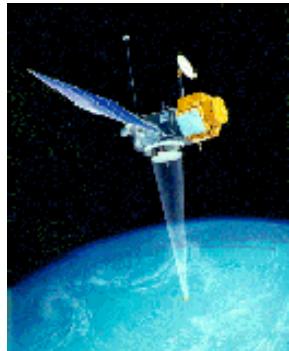




POD Calibration and Validation of the Precise Orbits for OSTM and Extending the TOPEX, Jason-1, and Jason-2 Climate Data Record

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Luthcke, T. Pennington, D.S. Chinn, B.D. Beckley, M.
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OSTST 2010 POD Splinter
Lisbon, Portugal
October 18-20, 2010





Meeting the OCEANOBS 2009 altimetry accuracy goal of 0.3 mm/yr in global mean sea level accuracy

Orbit accuracy goals from OCEANOBS 2009 Plenary Paper (Cazenave et al., 2009) :

- 1) Radial orbit accuracy to 1-cm or better
- 2) Mean radial drift over water 0.05 mm/y to 0.1 mm/y which is primarily due to the TRF *.
- 3) Other errors assumed sufficiently random and will not cause any appreciable sub-mm/y drift in orbit when averaged over time

* TRF stable 0.5 mm/y to 1 mm/y with about 10% erroneous effect on orbit radial drift over water.



Improving TP, J1, and J2 SLR/DORIS orbits with ITRF2008

Evaluate ITRF2008 SLR/DORIS orbit performance for TP, J1, J2 ¹

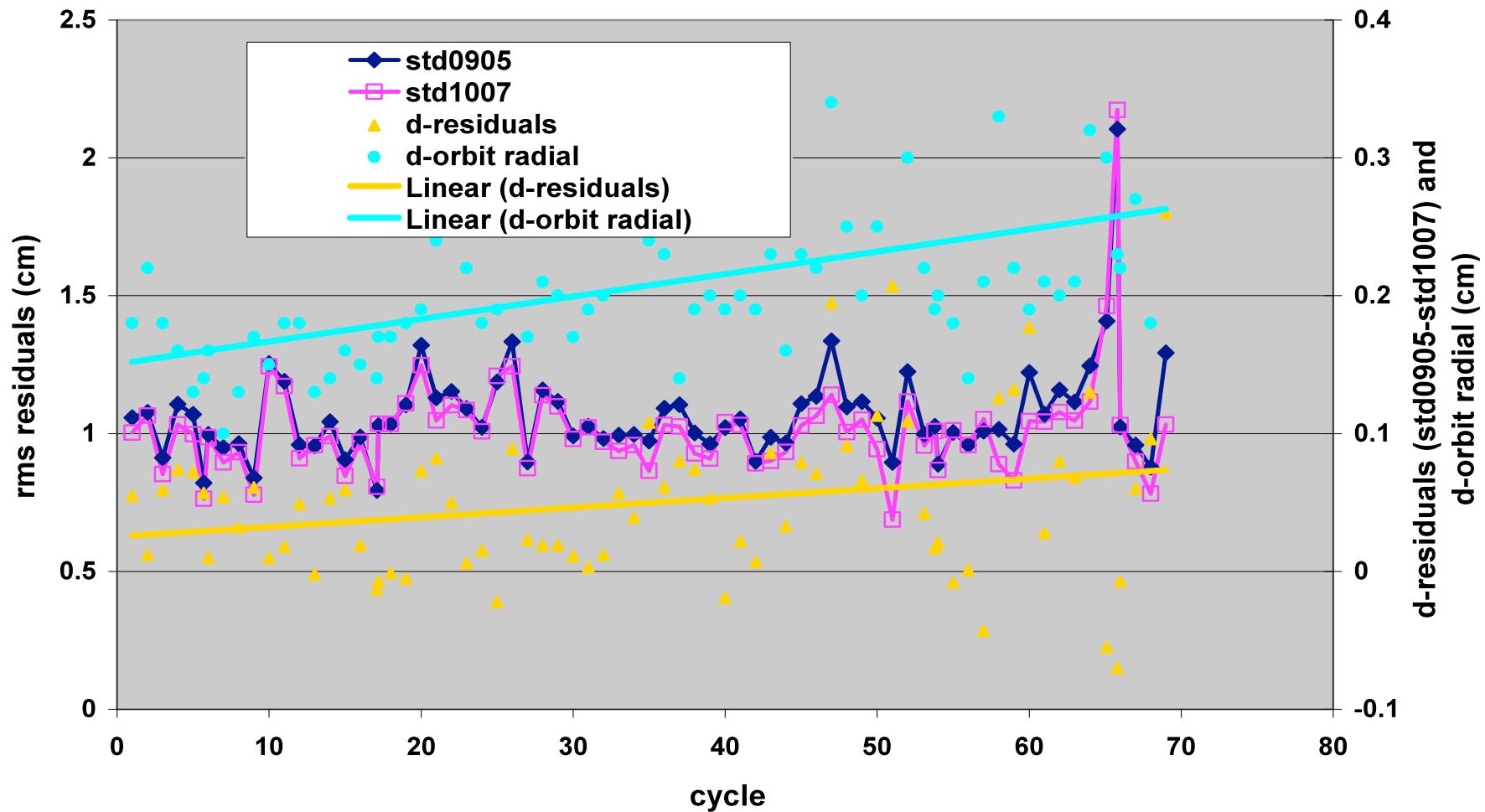
Mission	dynamic orbit test	average RMS tracking data residuals		
		DORIS (mm/s)	SLR (cm)	Crossover (cm) (independent)
TP cycles 1-446 xover: 30 cycles	std0905 (itrf2005)	0.4989	1.751	5.482
	std1007 (itrf2008)	0.4985	1.663	5.477
J1 cycles 1-259	std0905 (itrf2005)	0.3857	1.076	5.460
	std1007 (itrf2008)	0.3851	1.055	5.457
J2 cycles 1-75 xover cycles 1-52	std0905 (itrf2005)	0.3618	1.095	5.564
	std1007 (itrf2008)	0.3609	1.032	5.550

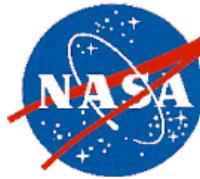
1) 1.5 cm radial accuracies have been achieved with the dynamic TP std0905 (itrf2005) orbits (Lemoine et al. 2010 , ASR, Towards development of a consistent orbit series for TOPEX, Jason-1, and Jason-2)



ITRF2005 degrades as we move into the future away from its solution span

J2 SLR residuals and radial orbit differences / cycle
(positive d-residuals imply improvement for std1007 (itrf2008))





Jason-2 reduced-dynamic orbits have achieved 1-cm accuracy, the dynamic are close

Evaluate Jason-2 orbit performance over cycles 1-50 (48)

test orbit <small>(residuals computed over same itrf2005 complement for each test orbit)</small>	average RMS tracking data residuals		
	DORIS (mm/s) itrf2005	SLR (cm) itrf2005	Crossover (cm) (independent)
gdrc (itrf2005-based)	0.3738	1.135	5.578
std0905 dynamic (itrf2005)	0.3738	1.148	5.551
std1007 dynamic (itrf2008)	0.3759	1.188	5.541
std0905 red-dyn (itrf2005) ¹	0.3730	1.106	5.500
std1007 red-dyn (itrf2008)	0.3751	1.153	5.484
jpl gps09a ²	0.3736	1.265	5.439
jpl gps10a	0.3758	1.243	5.412

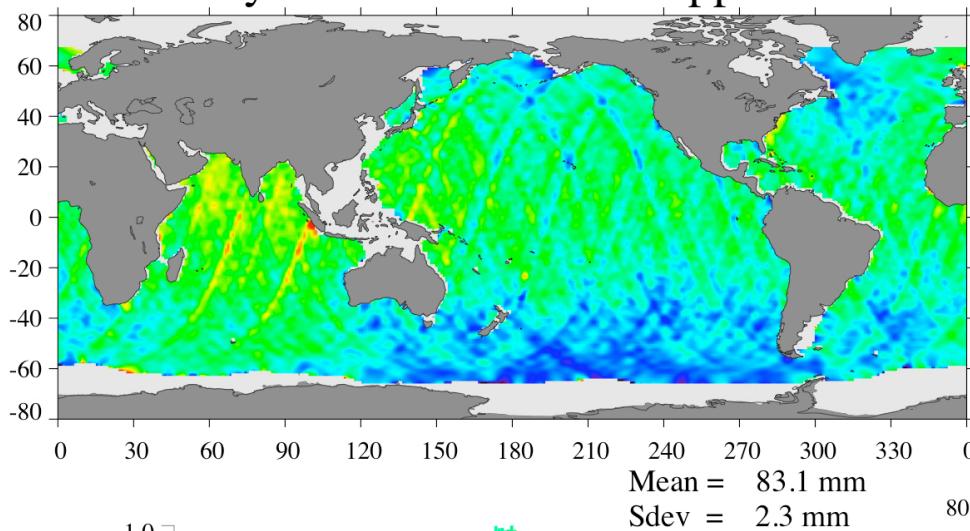
1) the std0905 reduced-dynamic orbits have achieved 1-cm accuracies (Zelensky et al. 2010 , ASR DORIS special issue)
2) the JPL GPS reduced-dynamic orbits have surpassed 1-cm accuracy (Bertiger et al., 2010. Marine Geodesy Jason-2 special issue)



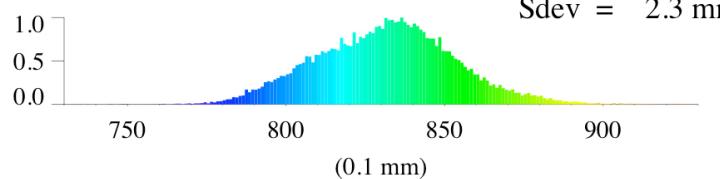
Orbit Consistency -vs- Accuracy

Jason2 - Jason1 Mean SSH cycles 1-20

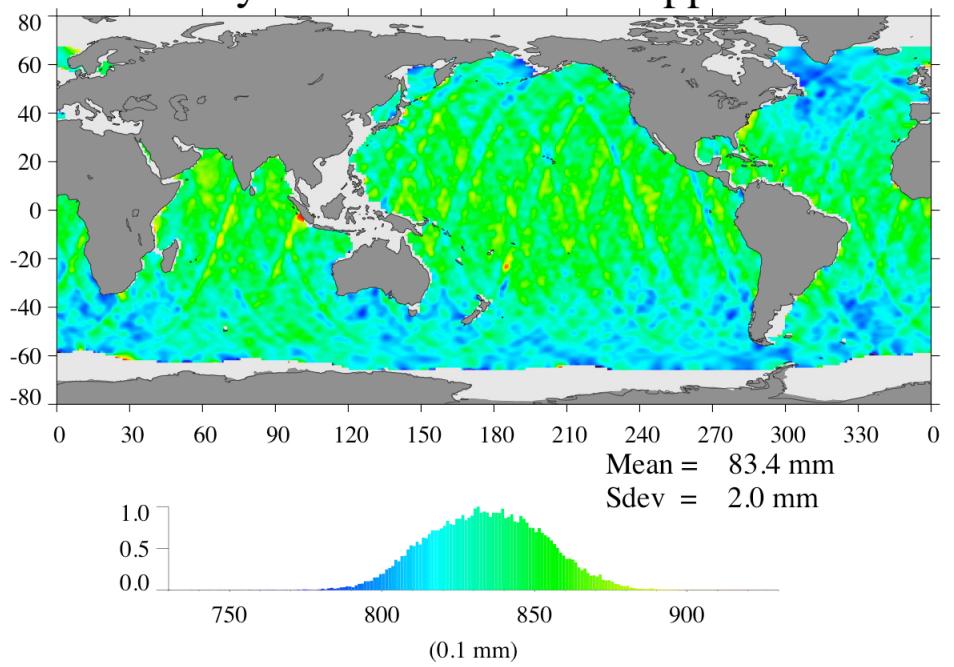
(itrf2008 orbits, no corrections)



J2 reduced_dynamic -
J1 dynamic orbits



J2 dynamic -
J1 dynamic orbits

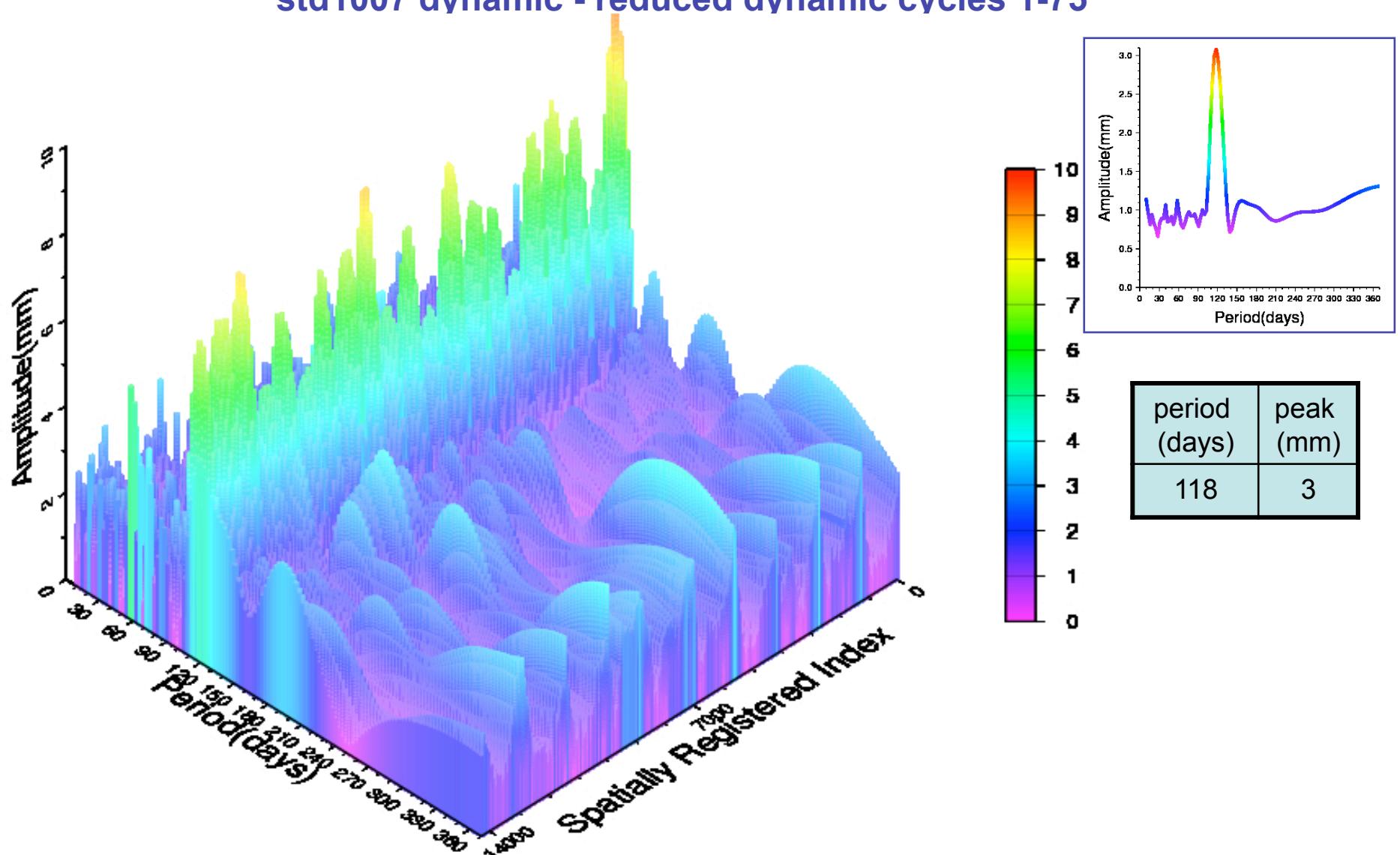




Remaining force model errors in J2 dynamic orbits

periodogram radial differences sampled over geographic points

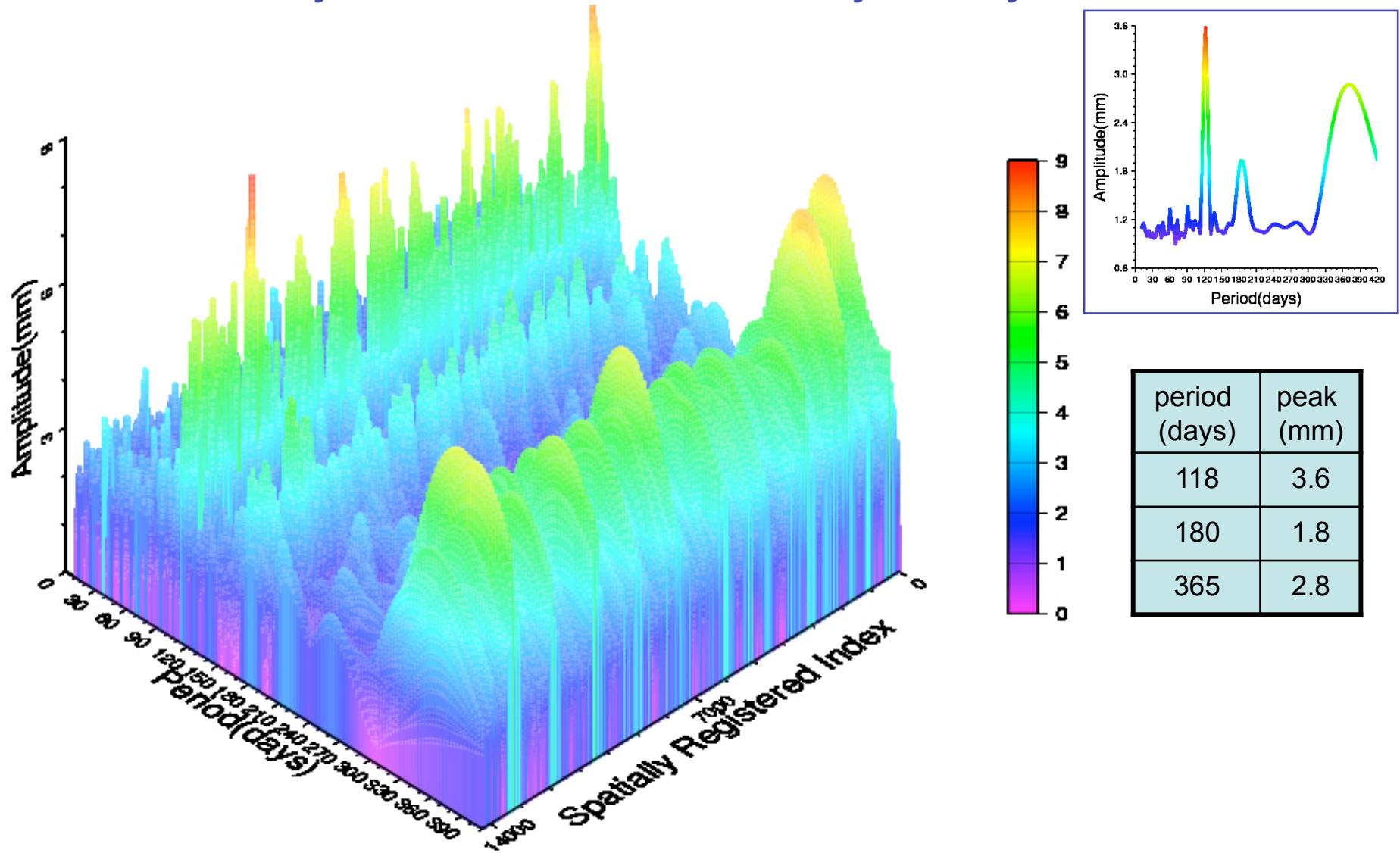
std1007 dynamic - reduced dynamic cycles 1-75





Remaining force model errors in J1 dynamic orbits

periodogram radial differences sampled over geographic points
GDRC dynamic - JPL GPS 7a reduced dynamic cycles 11-169

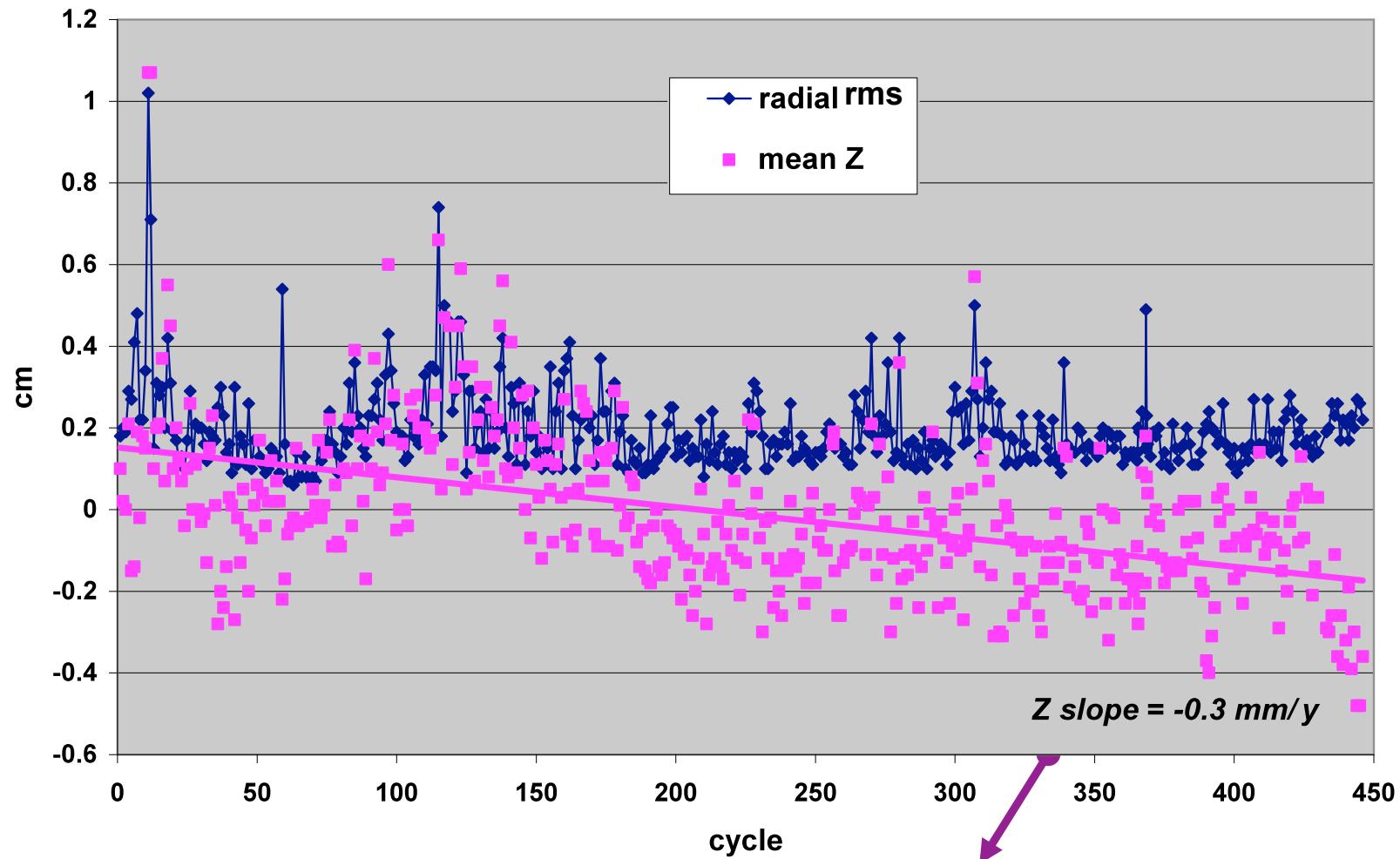




Sources of orbit instability - TRF realization

ITRF2005 - ITRF2008

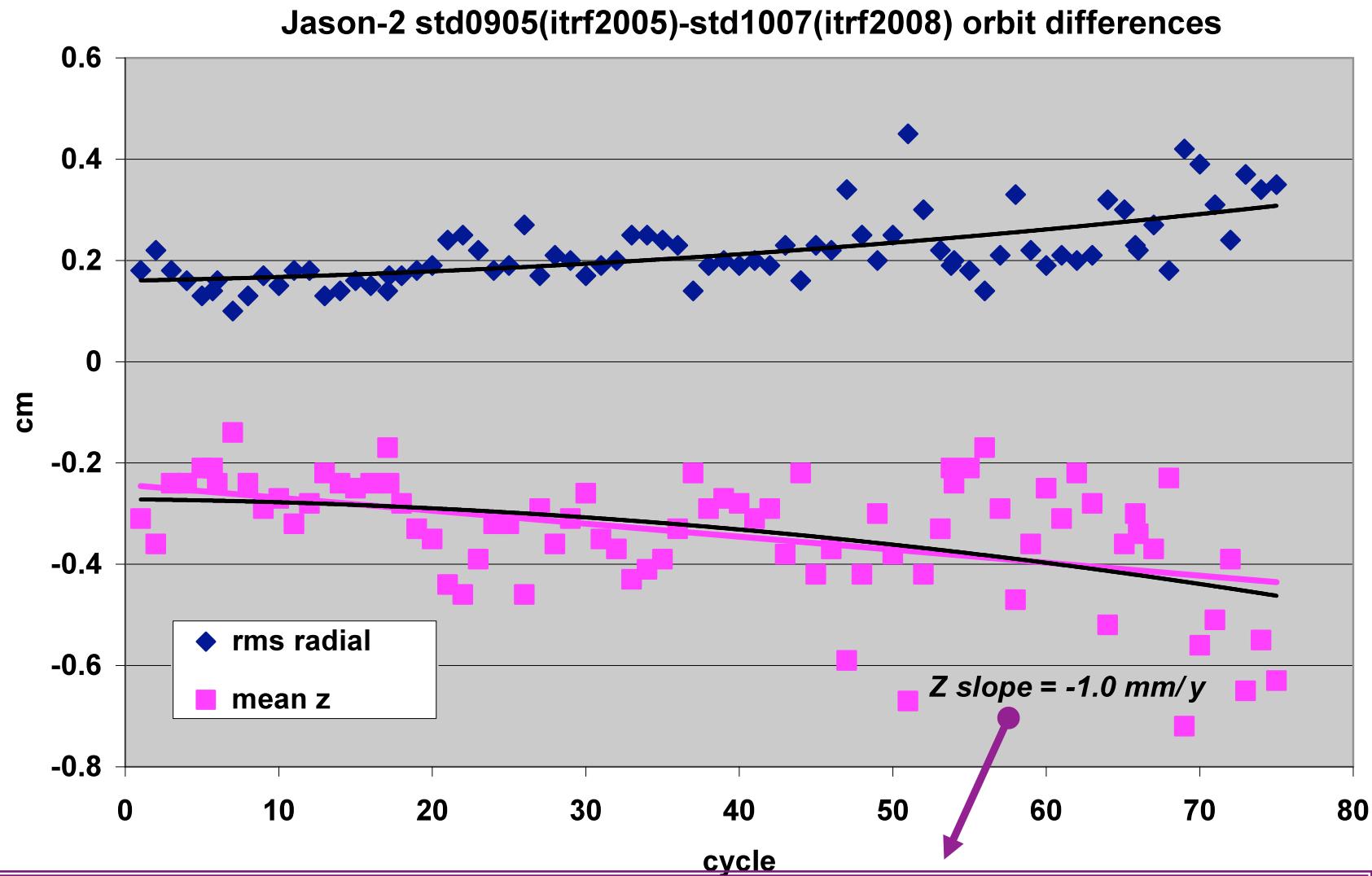
TP std0905 (itrf2005) - std1007 (itrf2008) SLR+DORIS orbit differences



Implies mean radial drift over water $\sim 0.06 \text{ mm/y}$ 1992-2004 (inside itrf2005 solution period)



Sources of orbit instability - TRF realization ITRF2005 - ITRF2008



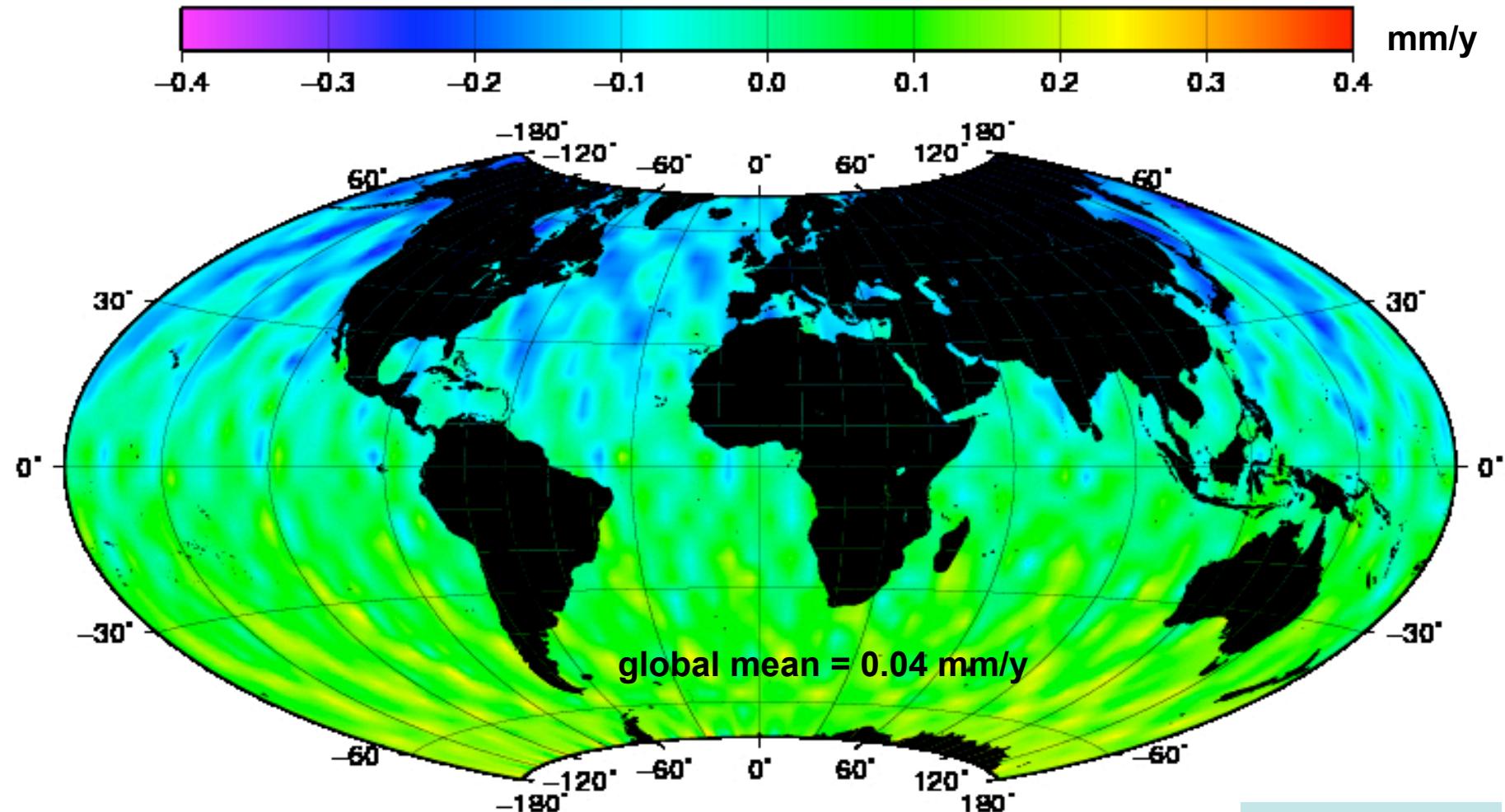
Implies mean radial drift over water ~ 0.2 mm/y 2008-2010 (outside itrf2005 solution period)



Sources of orbit instability - TRF solutions

J2 ITRF2008 (IGN) - ITRF2008D (DGFI)

estimated radial orbit linear trends, c1-75

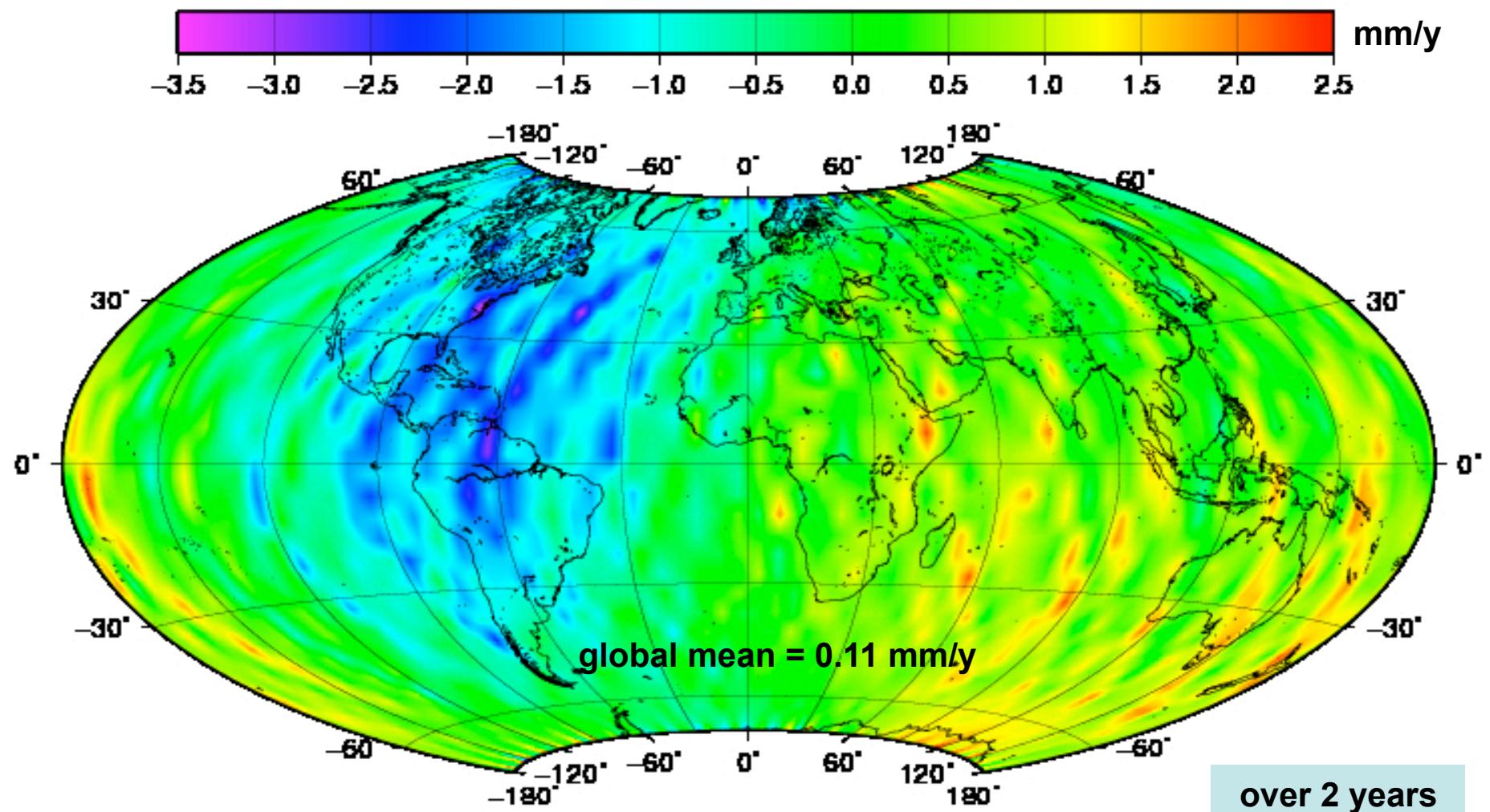




Sources of orbit instability - POD strategy

J2 itrf2008 dynamic-red_dyn est. radial
trends after removing 365d+180d signals

(same results after removing 365d+180d+118d signals)

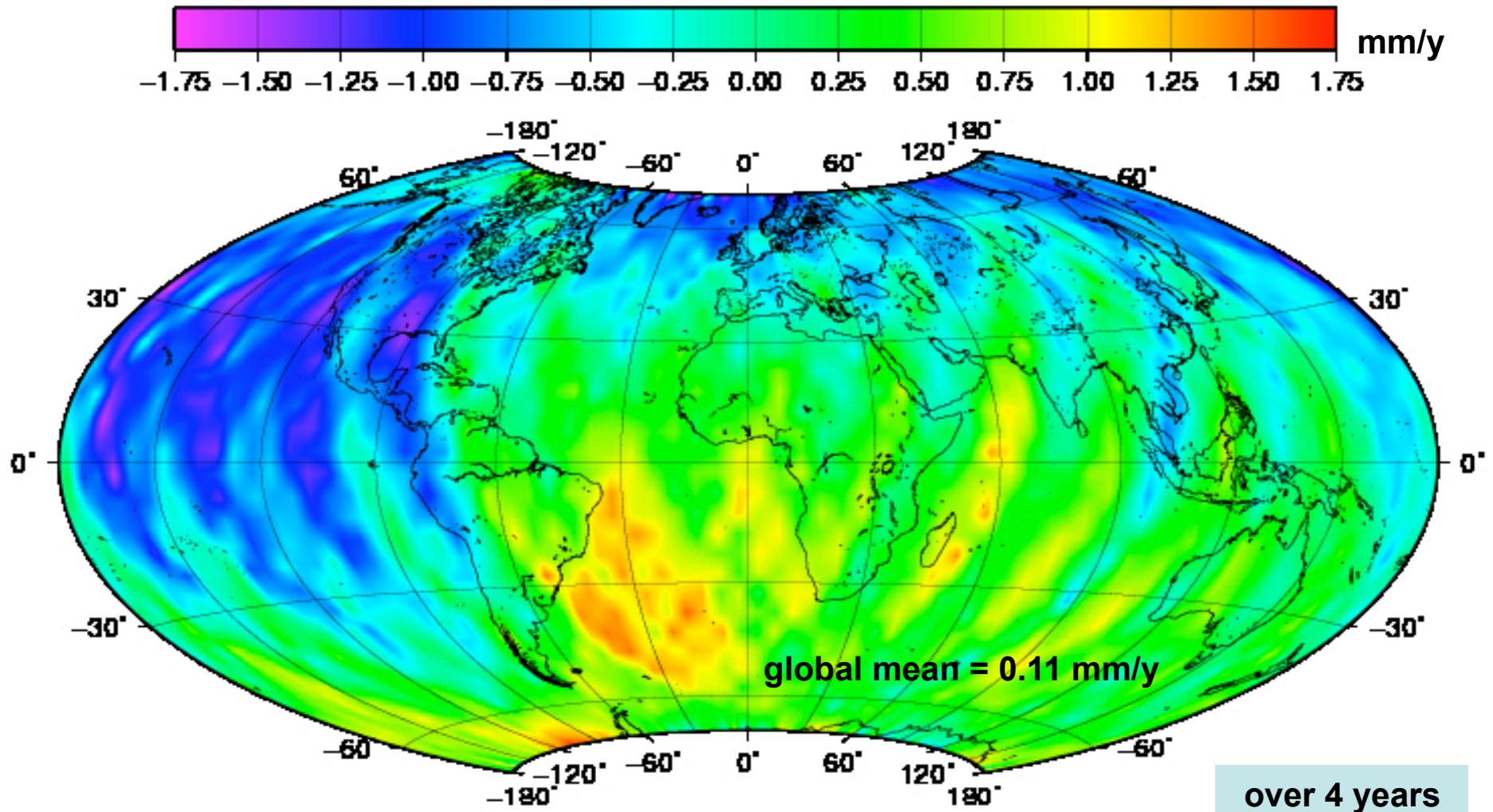




Sources of orbit instability - POD strategy

J1 GDRC - JPL GPS7a est. radial trends after removing annual+semi-annual signals

(same results after removing 365d+180d+118d signals)





Summary

- 1) SLR/DORIS ITRF2008 orbits show improvement over ITRF2005 across TP, J1, and J2 missions.**
- 2) *Have we achieved the OCEANOBS09 1-cm orbit goal?***
No, not across all missions. We see 1-cm J2 orbits and 1-cm J1 orbits cycles 8-169, however using the most accurate orbits raises the issue of consistency across missions.
- 3) *Have we achieved the OCEANOBS09 0.1 mm/y orbit stability goal?*** No. The causes for orbit instability are not well understood and include more than the TRF.



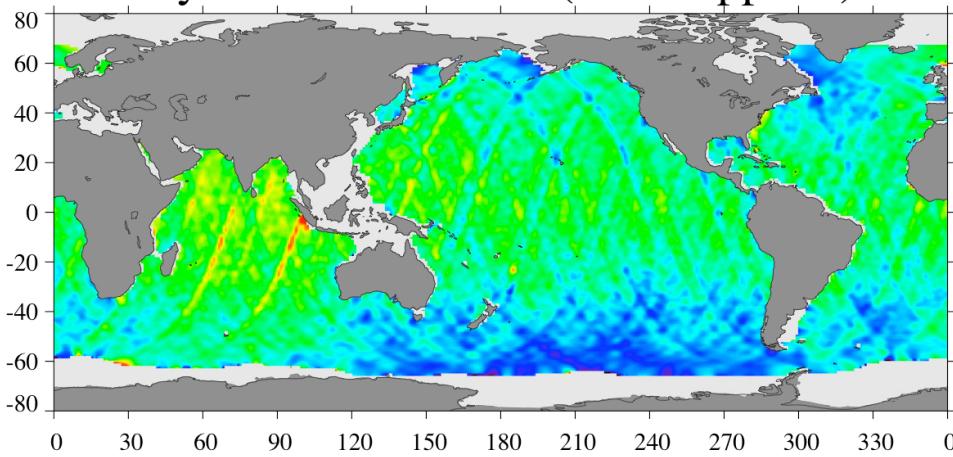
BACKUP



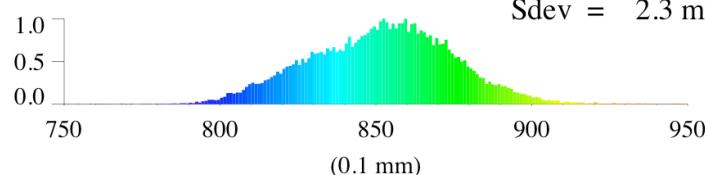


Orbit Consistency -vs- Accuracy

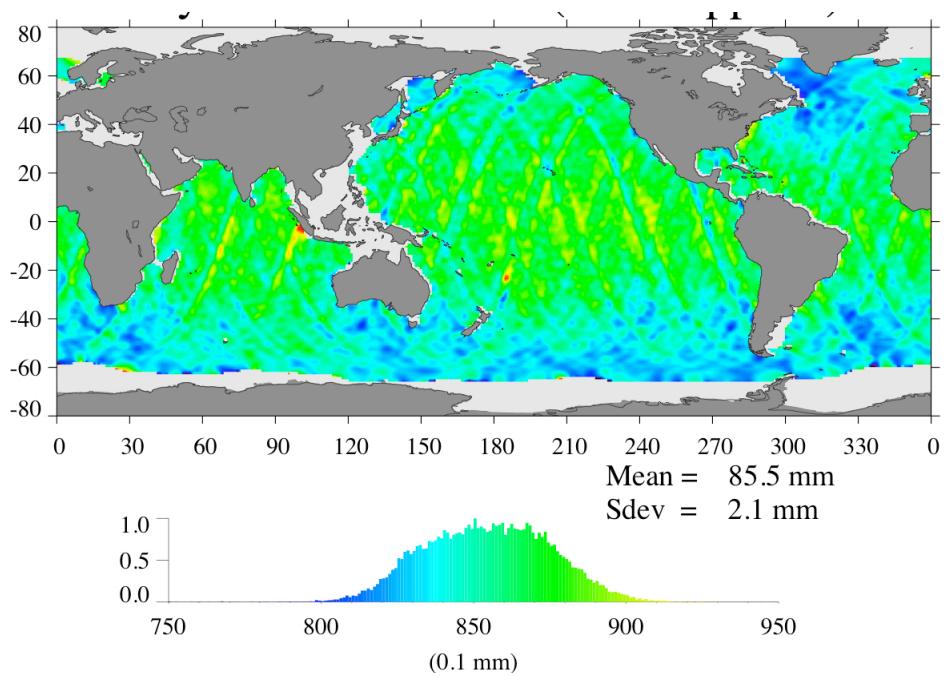
Jason2 - Jason1 Mean SSH cycles 1-20 (itrf2008, no corrections, SSB applied)



J2 reduced_dynamic -
J1 dynamic orbits



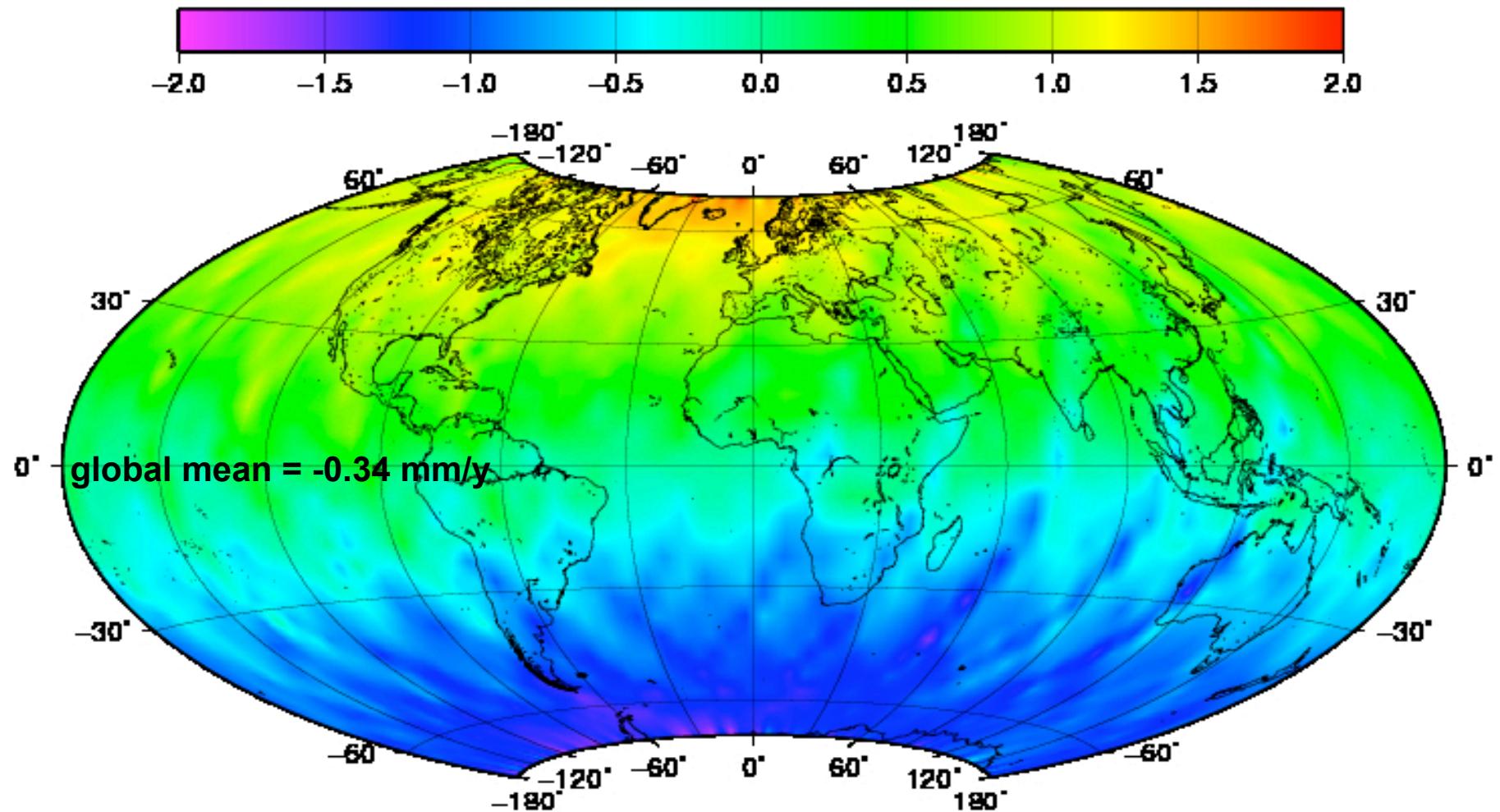
J2 dynamic -
J1 dynamic orbits





Sources of orbit instability –TRF realization

TP std1007 (ITRF2008) - GDR (CSR95)
estimated radial orbit linear trends, c11-340





Sources of orbit instability –TRF realization

J2 std0905(ITRF2005) – std1007(ITRF2008)

estimated radial orbit linear trends, c11-340

