# A demonstration of the potential of Cryosat-2 to contribute to mesoscale observation

## 1 – Abstract

Although the primary objective of ESA's Cryosat-2 is cryosphere science, the altimetry payload is operated globally on ocean.

This work illustrates that Cryosat-2 could be an asset for high-resolution (multi-mission) mesoscale observation.

While its orbit and payload are not ideal for oceanography, Cryosat can still capture 50% to 66% of the mesoscale variability observed with ENVISAT or Jason-1 in the Gulf Stream in near real time.

Cryosat-2 has the potential to mitigate the loss of old altimeters on operational NRT applications.

Reference: http://dx.doi.org/10.1016/j.asr.2011.07.002

## 2 - Methodology Data used:

30 days of Cryosat-2 data generated by the Cryosat-2 Processing Prototype (CPP) from CNES (20 Hz, GDR-like)

LRM mode only (no doppler/SAR data used)

DUACS along-track SLA for Jason-2, Jason-1, and ENVISAT Period used: late October to

late November 2010

« Truth » from Jason-2 + Jason-1

F1 : Maps of sea

22/11/2010 and

at-2

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## Data preprocessing:

Update of ancillary corrections (e.g. tropo, tides...)

20 Hz validation, filtering and compression to 1 Hz

Global Cal/Val editing

Crosscalibration with Jason-2 as a reference (standard DUACS processor, ENVISAT

used as a model for parameters) Generation of along-track sea

level anomalies (vs gridded MSS CLS/CNES 2011)

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#### Processing and analyses:

Generation of multi-mission maps of SLA (from 1 to 4 satellites, with / without Cryosat)

Comparison between maps with Cryosat and independent along-track measurements from the Jason tandem

Comparison between configurations (1 to 4 sensors)

Comparison to SST and OC

What/Where is the mesoscale content from Cryosat ?

### 3a – Qualitative improvements

Adding Cryosat to ENVISAT maps substantially changes the shape and intensity of mesoscale features in the Gulf Stream (F1). Cryosat improves the consistency with independent maps from the Jason tandem.



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Comparisons between absolute topography from Cryosat + ENVISAT and SST or Ocean Color confirm (F2) that the contribution from Cryosat is beneficial (e.g. better shape of eddies and fronts).

F2 : Comparison of SST nd chlorophyll entration cor s with the map of lute dynamic graphy built from ENVISAT and Cryosat-2 aps are compute n 22/11/2010 Units : "C, mg/m<sup>3</sup>. cm.





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# 4a – Limitation: sampling

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Cryosat's orbit is geodetic (one year repeat cycle) with a 30-day sub-cycle (global homogeneous sampling), but no sub-cycle in the 7 - 15 day range. The resulting NRT sampling is extremely irregular (F6) if one wants to observe mesoscale (decorrelation in ~15 days).

As a result, the innovative content brought by Cryosat into multi-satellite NRT maps (F7) is located in 500 km wide bands alternating with 500 km wide "blind spots". The bands propagate westwards (~50 km / day).

To infer the local (in each grid point) contribution of Cryosat in a 4-sensor map, we performed a degrees of freedom of signal analysis in the mapping OI.

While Cryosat's contribution is 20% in average, the DFS analysis confirms that it is primarily located in these 500 km bands, which largely contrasts with the spatially homogeneous contribution of all other missions (F8).







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F7 : Difference in cm between a sea level map built from with Cryosat-2 and a map built without it computed on 22/11/10. Non-zero differences are aggregated ar recent Cryosat measurements (black lines). Unit : cm.

F8 : Fraction of the 4-satellite map that is ally derived from Cryosat-2 (left) and Jason2 (right). Computed from a Degrees of Freedom Analysis (DFS) performed at each grid point (0.5 = 50%).

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We interpolated ENVISAT and ENVISAT+

actual along-track measurements (IGDR)

Cryosat maps on Jason tracks. From

The 4-sensor map is the best topography estimate in near real time. From differences to this reference, we can infer (F5) the improvement (reduction of difference RMS) from each satellite in constellations with 2 or 3 sensors.

Cryosat can capture about 50 to 66% of the mesoscale content seen by Jason or ENVISAT



F5 : RMS of the differences een the "optimal" Near Real Time maps computed with 4 altimeters, and Near al Time maps built from



ong-track topography urements (red) from Jason1 (top) and Jason2 (bottom) with interpolated m from ENVISAT alone (blue) and ENVISAT + Cryosat (green). Unit: m. Difference between

Magine	Cyclic	Ppin.	Apr. (unMap)	actual measurements (m)		
				Invite	ElevityLT = Crymat	MME of improvement int
195061	325	176	9	0.13	0.09	0.09
	325	202	8	0.14	0.13	0.04
[asce]	226	217	7	0.15	0.15	0.11
lasce1	326	252	6	0.06	0.05	0.02
lasee1	327	13	5	0.11	0.11	0.03
Lasce 1	327	24	5	0.15	0.08	0.12
lascel	327	22	-	0.08	0.07	0.05
lasce1	327	222	2	0.12	0.09	0.08
lason2	87	- 29		0.38	0.13	0.12
Lasce2	87	300	7	0.08	0.05	0.05
lasee2	87	115		0.32	0.10	0.02
lasce2	87	291	3	0.06	0.05	0.00
Lasce2	- 87	202	3	0.17	0.07	0.15
Lasce2	- 37	217	2	0.06	0.05	0.09
		1	i.e.	0.12	0.09	0.02

F4: Along-track differences between actual measurements from the Jason tandem, and nterpolated values of ENVISAT maps and ENVISAT+Cryosat-2 maps. Column #7 gives the RMS of the improvement observed from using Cryosat-2 measurements. Unit: m.

F9 : Map of the mo

ved from DUACS

tellite maps. Unit: cm

# 1 to 3 satellites. Unit: cm.

# 4b – Limitation: error budget

Cryosat's orbit and payload were designed for Cryosphere observation. This significantly increases Cryosat's error budget on ocean despite the very good behavior of SIRAL and DORIS.

To infer the importance of this additional error, we have compared oceanic variability (F9) to a gross approximation of the additional error

budget that is specific to Cryosat (F10) : By comparing ECMWF wet troposphere

- to the radiometer correction from ENVISAT
- By comparing GIM-based ionosphere to

 By using the formal error map of the gridded CNES/CLS MSS reference (non repeat orbit)



F10 : Quadratic sum of the ionosphere, wet troposphere and MSS error budgets used for Cryosat-2 in the mapping process. Expressed in cm RMS (top) and (bottom) in percentage of the oc variability map from Fig.9

 Perspectives There are two major perspectives to this successful demonstration:

1 - Exploitation of the SAR/doppler mode to cover high latitudes (e.g. Arctic) with 2 altimeters for the first time ever.

2 – Transition to operational NRT production (prototype processor ready and configured)

High quality L2 data (LRM+SAR) are needed

the dual frequency correction from Jason-2