

## **AN IMPROVED OBJECTIVE ANALYSIS SCHEME OF SCANNING RADIOMETER MEASUREMENTS TO COMPUTE THE WATER VAPOUR PATH DELAY FOR ALTIMETRY**

*Jacques STUM\**, *Antoine Delepouille\**, *Philippe SICARD\**  
*and Amandine Guillot\*\**

(\*) Collecte Localisation Satellites, 8-10 rue Hermès, 31520 Ramonville, France

(\*\*) Centre National d'Etudes Spatiales, 18 avenue Edouard Belin, 31055 Toulouse,  
France

# Introduction

- Atmospheric water vapour induces path delay to pulses emitted by spaceborne radar altimeters to measure sea surface height
- Most altimeter missions embark a MWR to compute this path delay. ECMWF analyses may also be used, but are less accurate, and at a lower resolution
- As an alternate approach, objective analysis of all existing scanning MWR to compute the WV path delay for altimetry looks promising (see Stum et al, IEEE Geos Rem Sens, 2011)
- This talk is devoted to recent improvements of the method, and to its application to operational NRT altimeter data processing

# Summary

1. From integrated water vapor products to wet tropospheric correction
2. Available observations
3. Errors characterization
4. Revisit of Stum, 2011 for variance and correlation radii
5. Validation over 1 year JMR data
6. Application to NRT over current IGDR Jason-2 data
7. Conclusions

## From water vapor to wet tropospheric correction

- Water vapour observations over the ocean can be provided by scanning microwave radiometers

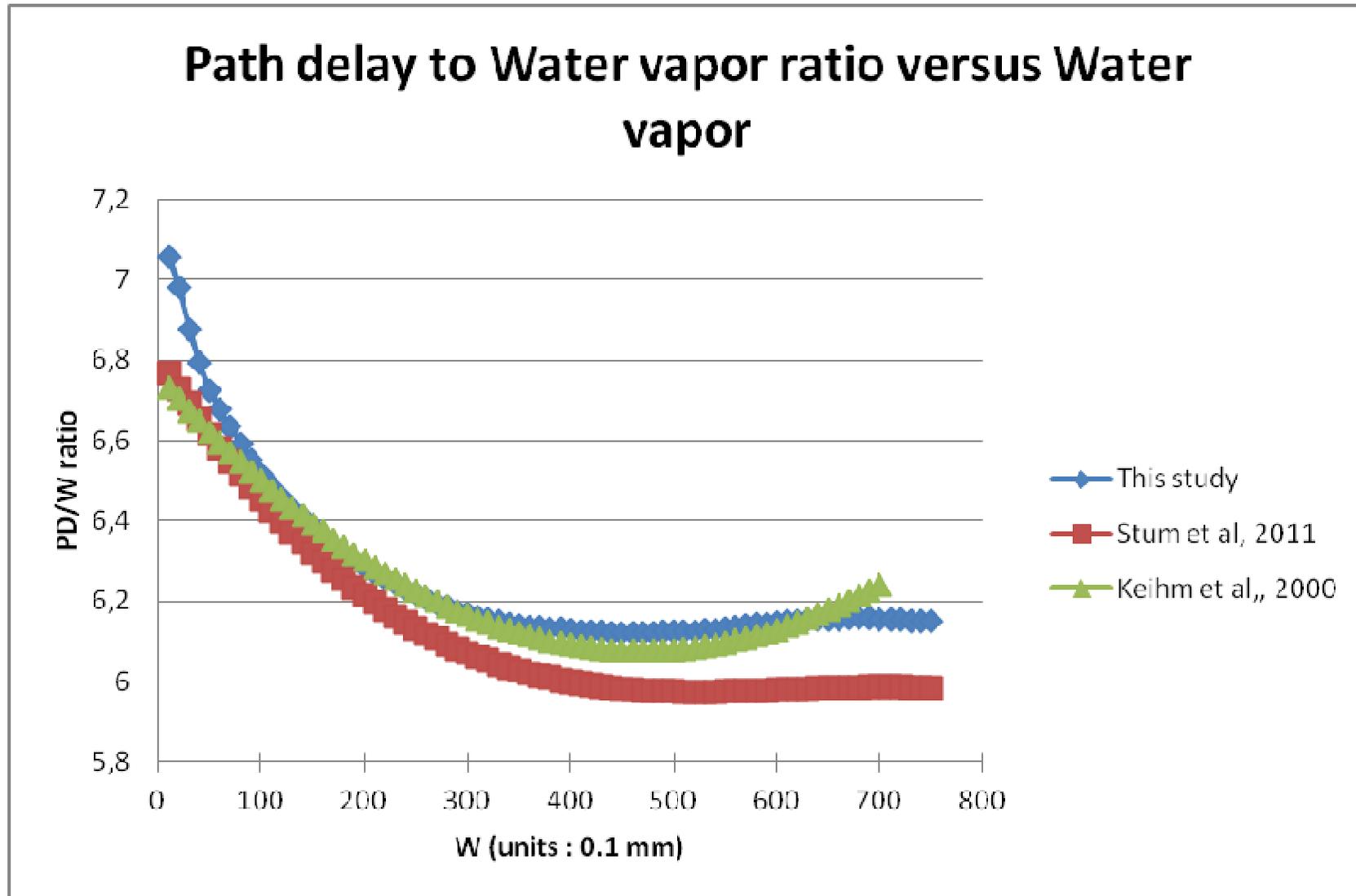
- Need first to be converted into path delay

- We start from  $W = \int_0^H \rho_v dz$

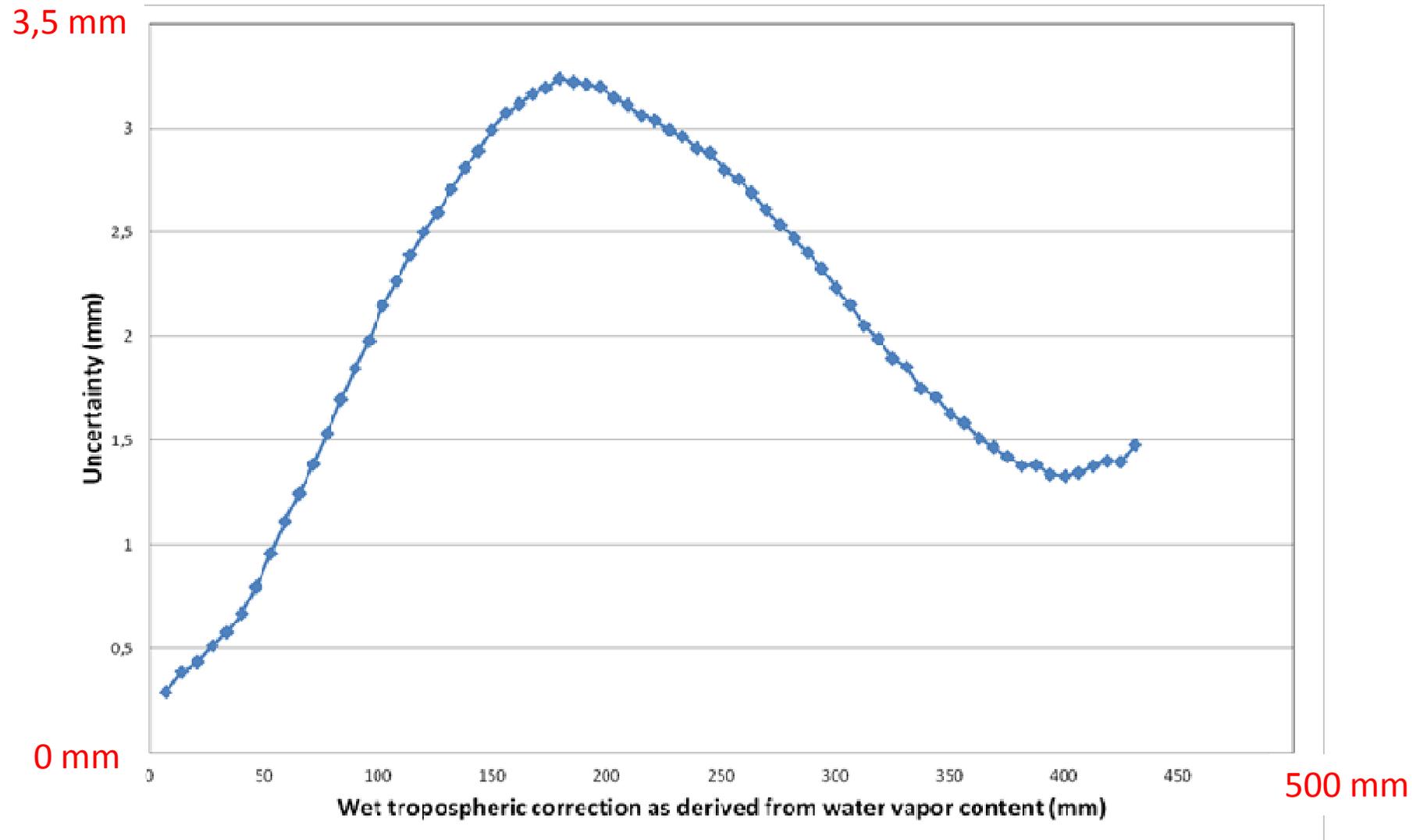
- We need to compute  $PD \approx 1720.6 \times \int_0^H \frac{\rho_v}{T} dz$

- 4 months of ERA-Interim temperature and humidity profiles to compute (and tabulate) the PD/W ratio

# Related uncertainty



## Uncertainty of the wet tropo as derived from water vapour



# Scanning microwave radiometers

**12** microwave scanners available in 2008 :

- 5 AMSU-A :
  - NOAA-15, NOAA-16, NOAA-17, NOAA-18, METOP-A
- 3 SSMI :
  - F13, F14, F15
- 2 SSMI/S :
  - F16, F17
- AMSR-E
- TMI

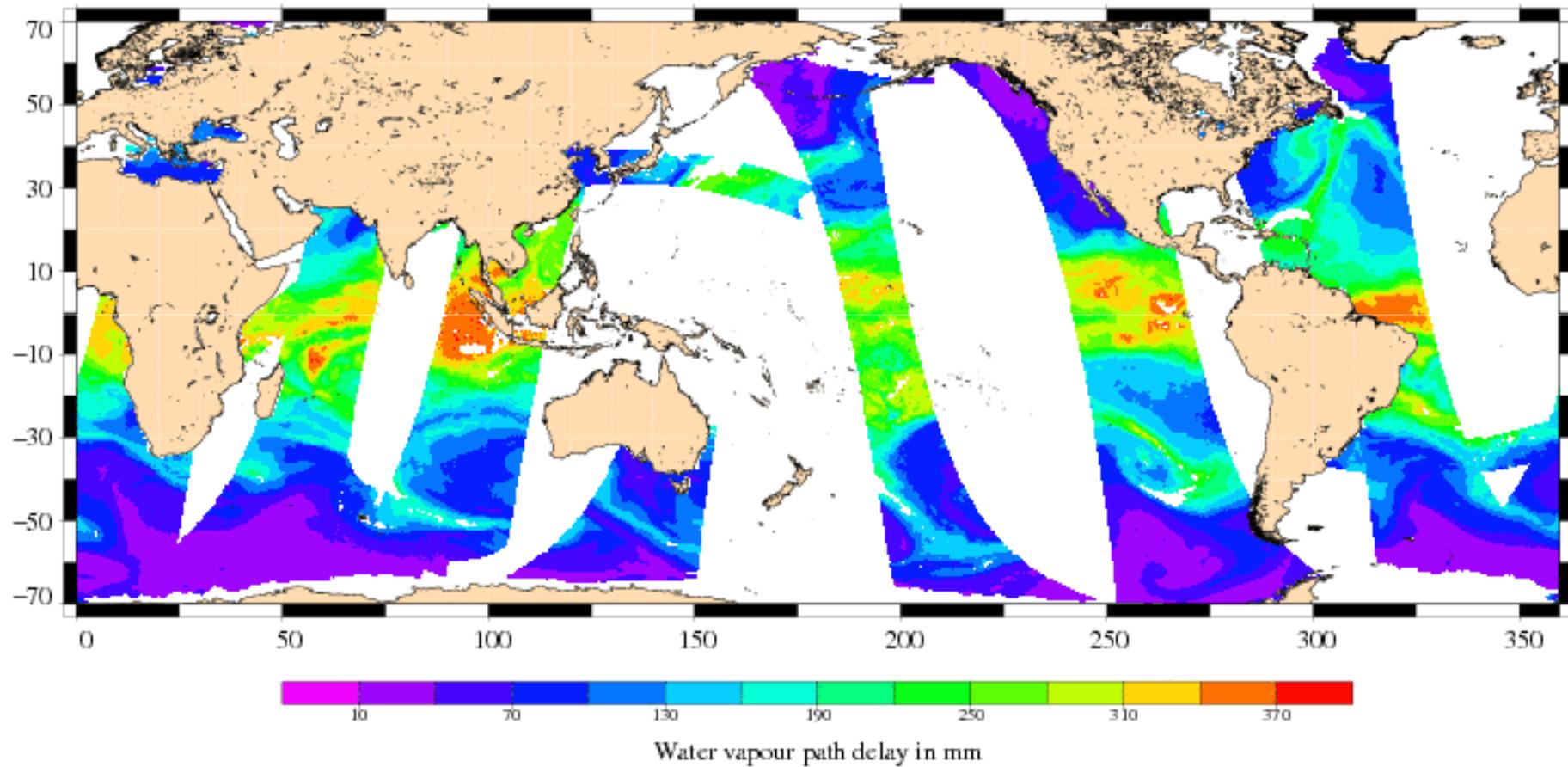
## Data products and Providers

- AMSU-A : level 2 products from NOAA CLASS
- SSMI : level 2 products from NOAA CLASS and level 3 daily products from RSS
- SSMI/S : level 1B (NetCDF SDR) from NOAA CLASS and level 3 daily products from RSS
  - Goal : to chose the best SSMI provider for OA
- TMI : level 2 products from GHRC
- AMSR-E : level 2 products from NSIDC

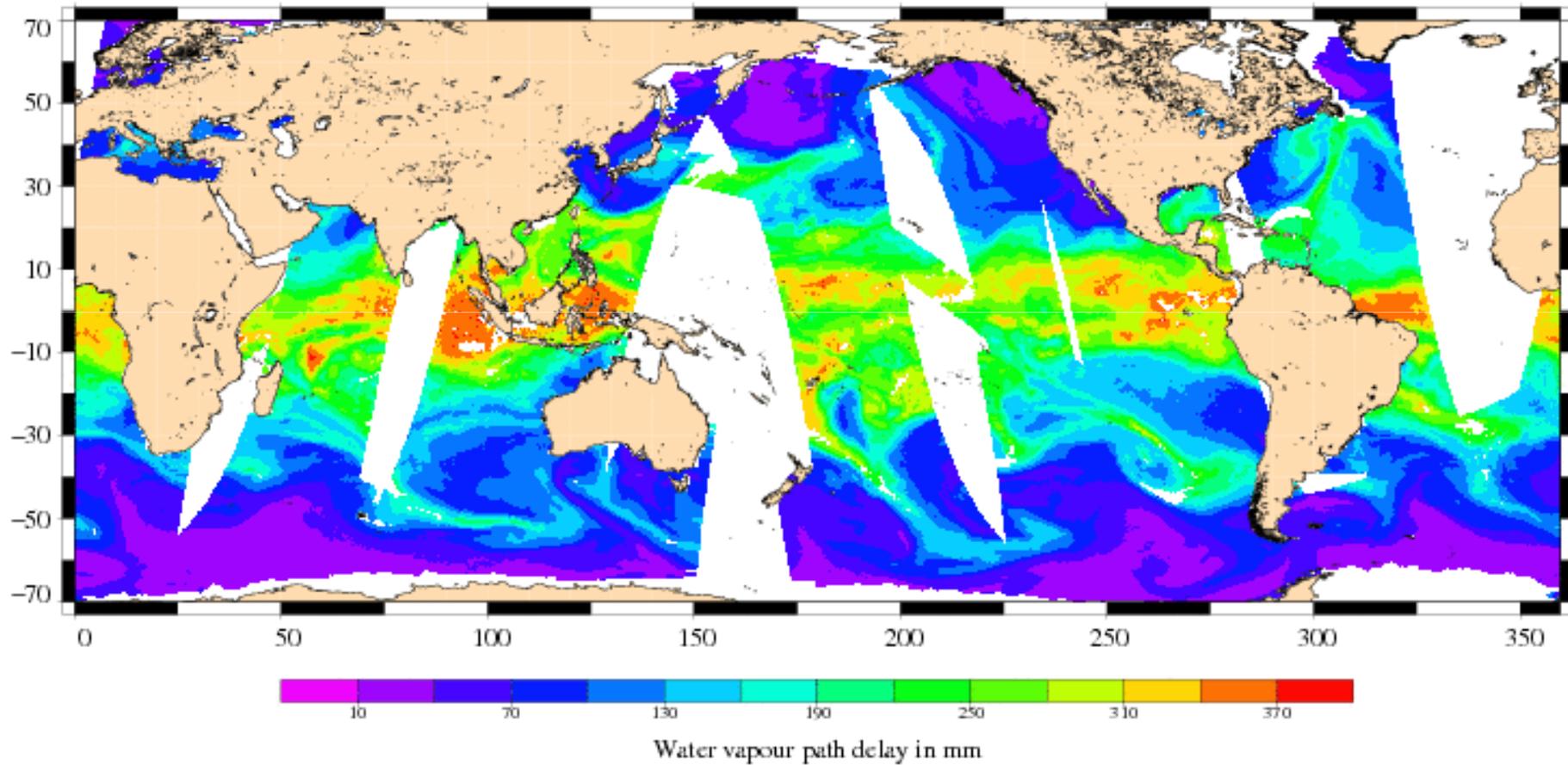
# Microwave radiometer data editing

- Use of product quality flags often lead to over (under) estimated ice concentration
- Choice of a common external sea ice mask derived from the OSI/SAF sea ice concentration daily files : improves product data quality
- Revisiting the use of product rain flags to better edit data contaminated by rain

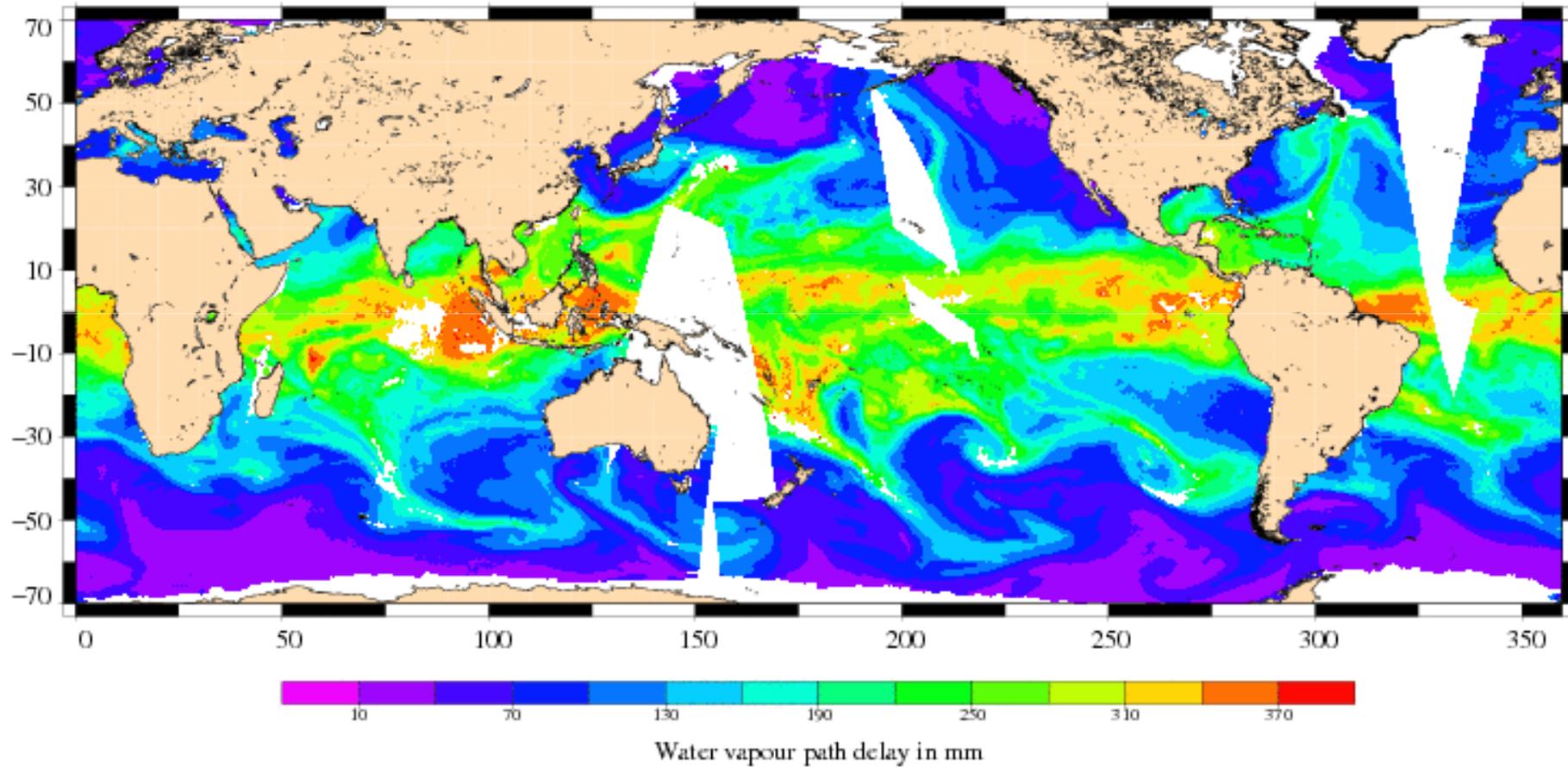
### All-sensor coverage within 1 hour (47%)



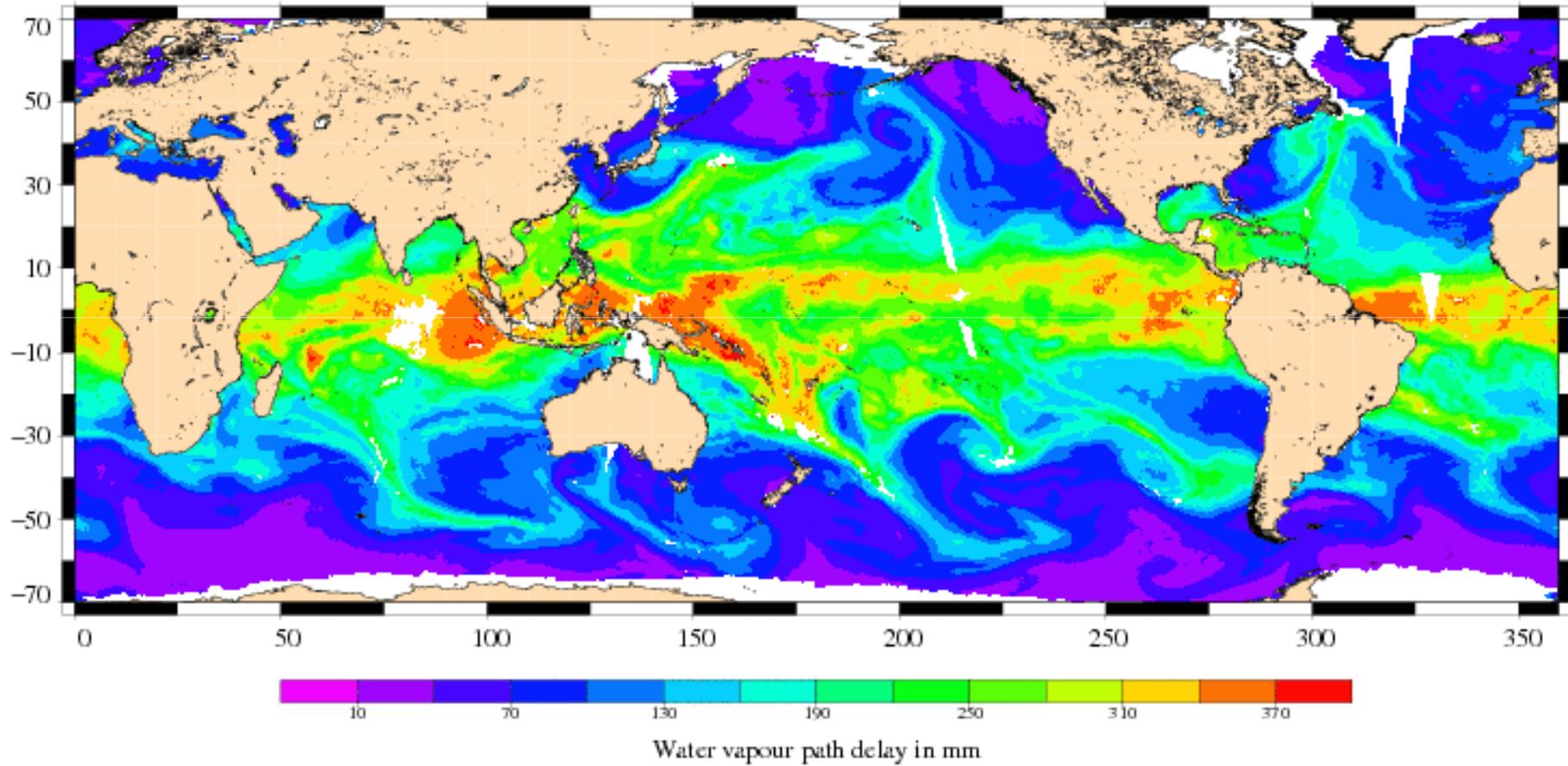
### All-sensor coverage within 2 hours (71%)



### All-sensor coverage within 3 hours (84%)

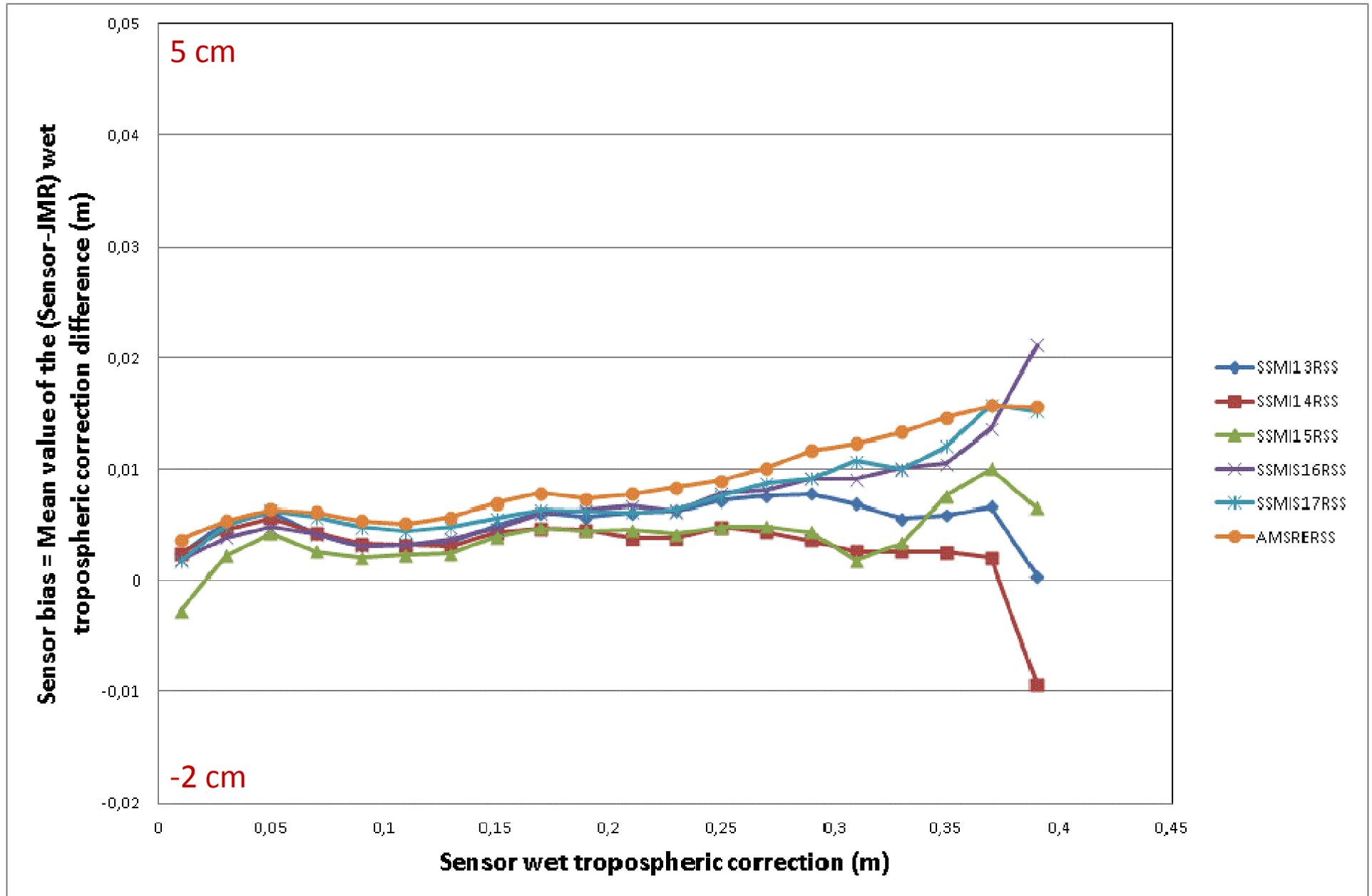


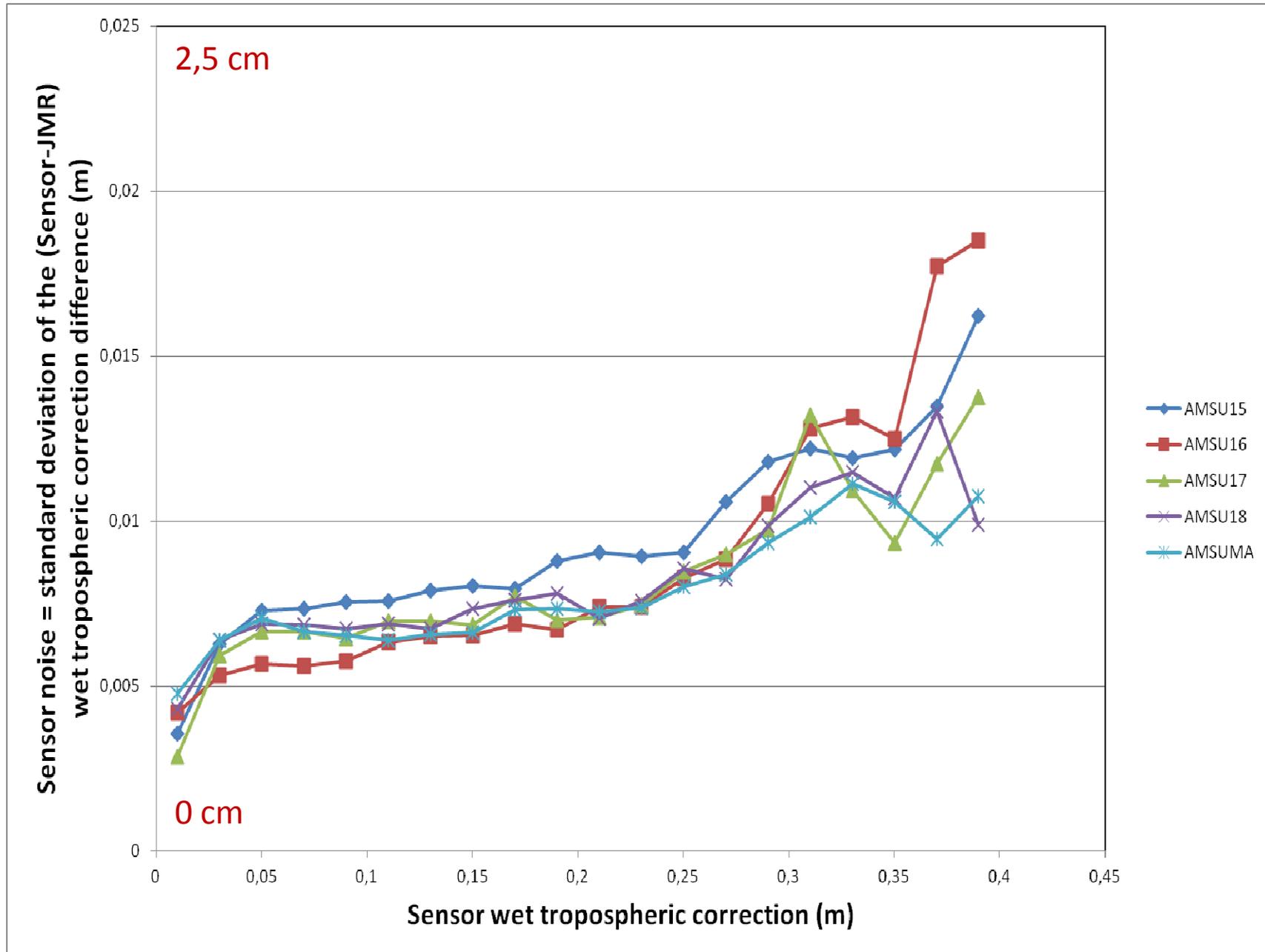
All-sensor coverage within 4 hours (92%)



# Sensor PD **bias** and **noise** characterization

- Jason-1 microwave radiometer (JMR) taken as a reference
- Sensor-JMR matchups : bilinear interpolation at JMR location of the four sensor surrounding pixels, with less than half an hour time lag
- Global statistics of the (sensor – JMR) PD difference over 12 Jason-1 cycles (4 months)





# Sensor **bias** and **noise** characterization

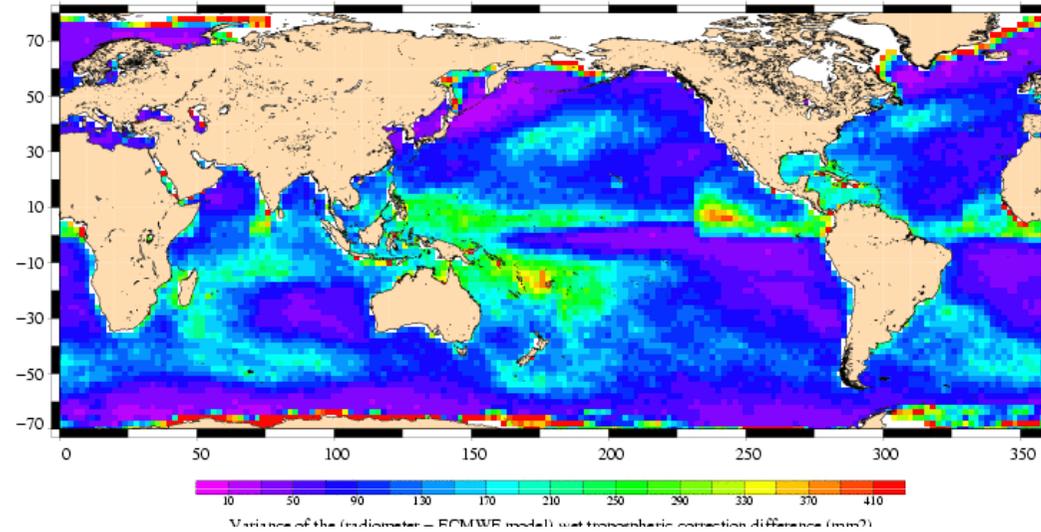
- Conclusions
  - SSMI/SSMIS :
    - NOAA Level 2 products are less accurate than the RSS Level 3 ones.
    - Despite the better coverage of NOAA products, RSS provider chosen.
  - AMSR-E is the most accurate sensor
  - AMSU-A are the less accurate ones but provide good coverage

## Variance and correlation radii

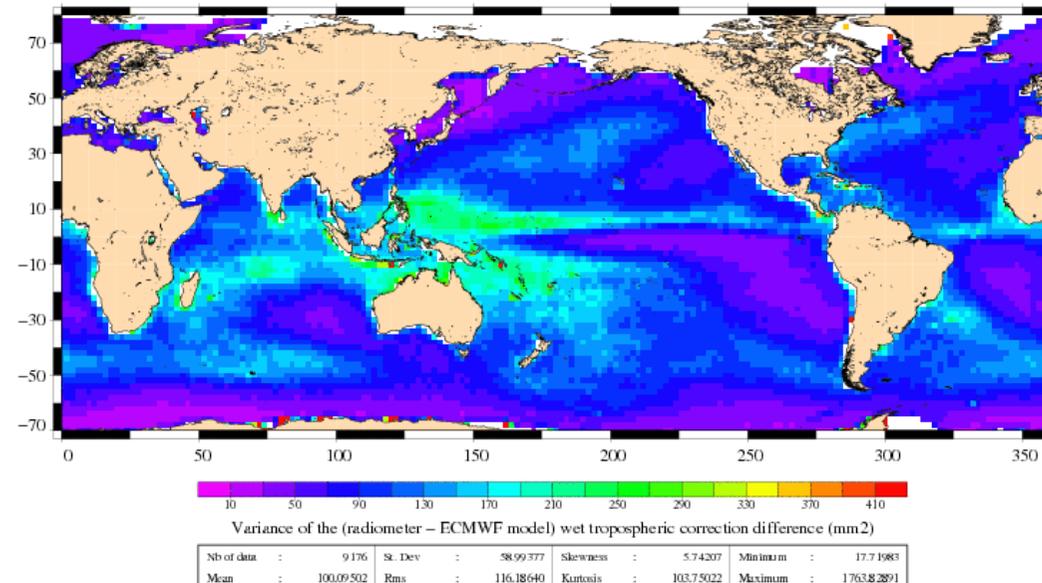
- Estimation of the variance and correlation radii of the anomalies (sensor PD – ECMWF PD) revisited :
  - Benefit from the increased number of sensors (12 versus 7 in Stum et al., 2011)
  - Also benefit from the improved data editing

From  
Stum et  
al, 2011

12-hourly, 2°x2° Variance of the (radiometer – model) wet tropospheric correction difference  
January 2008 mean



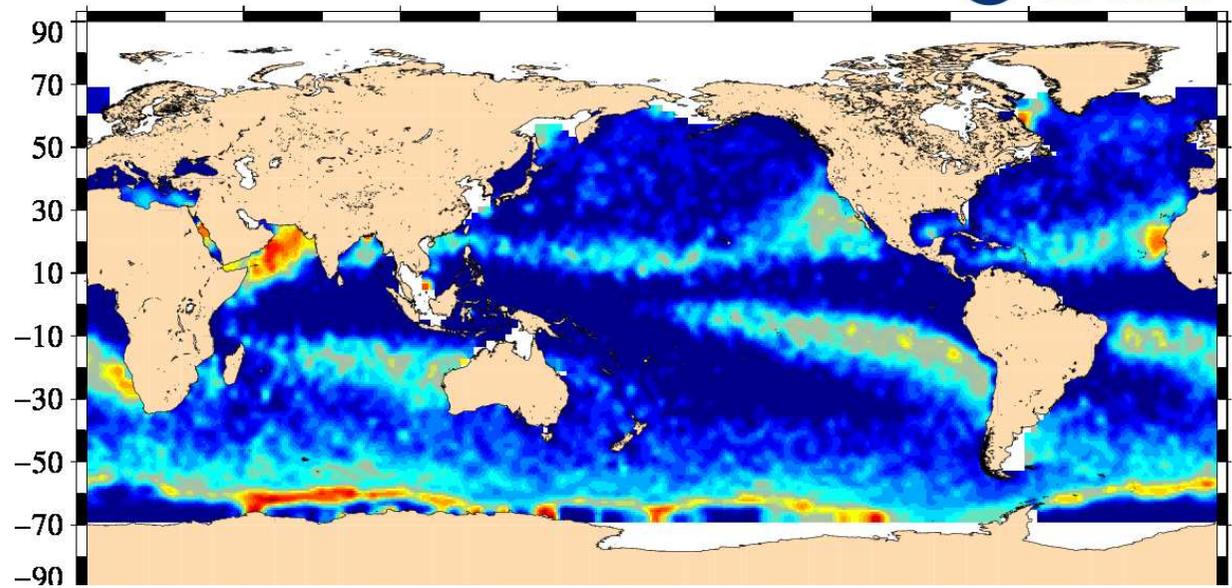
This study



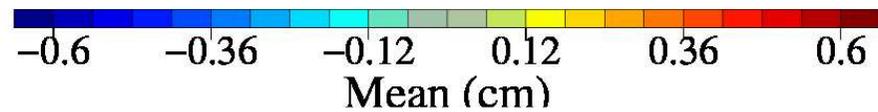
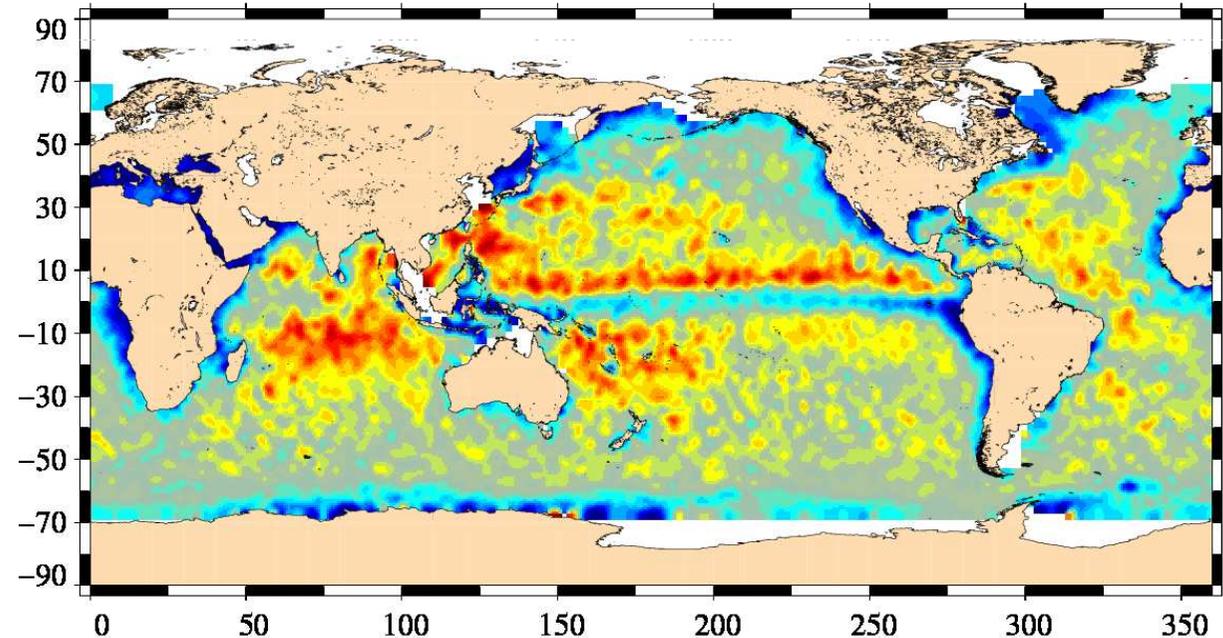
# Validation

- OA run over year 2008 (Jason-1 cycles 221 to 256)
- OA wet tropo correction compared to JMR and ECMWF wet tropo
  - Along track statistics
  - Crossover statistics

Mean of  
(ECMWF – JMR)

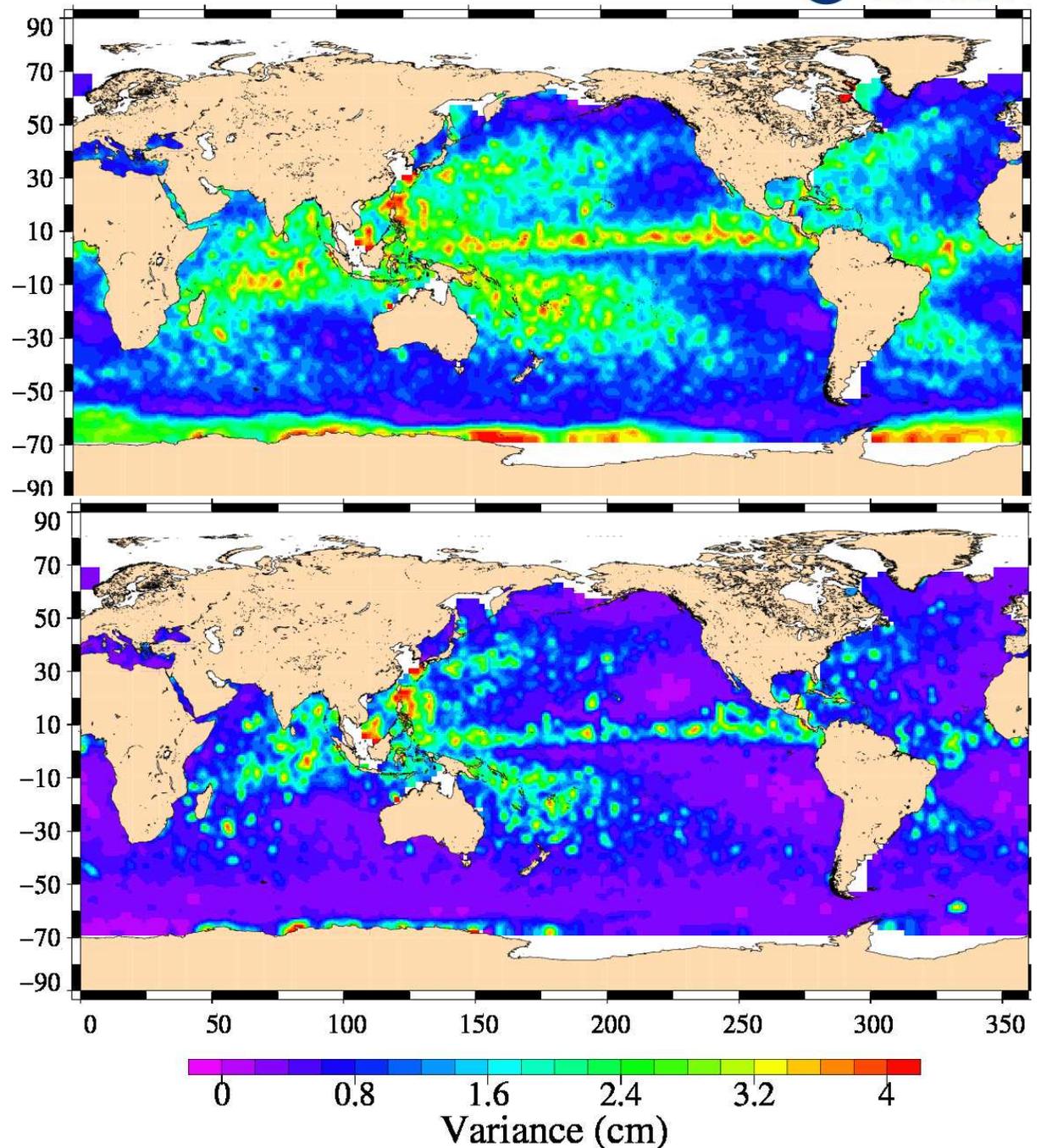


Mean of  
(OA – JMR)



Variance of  
(ECMWF – JMR)

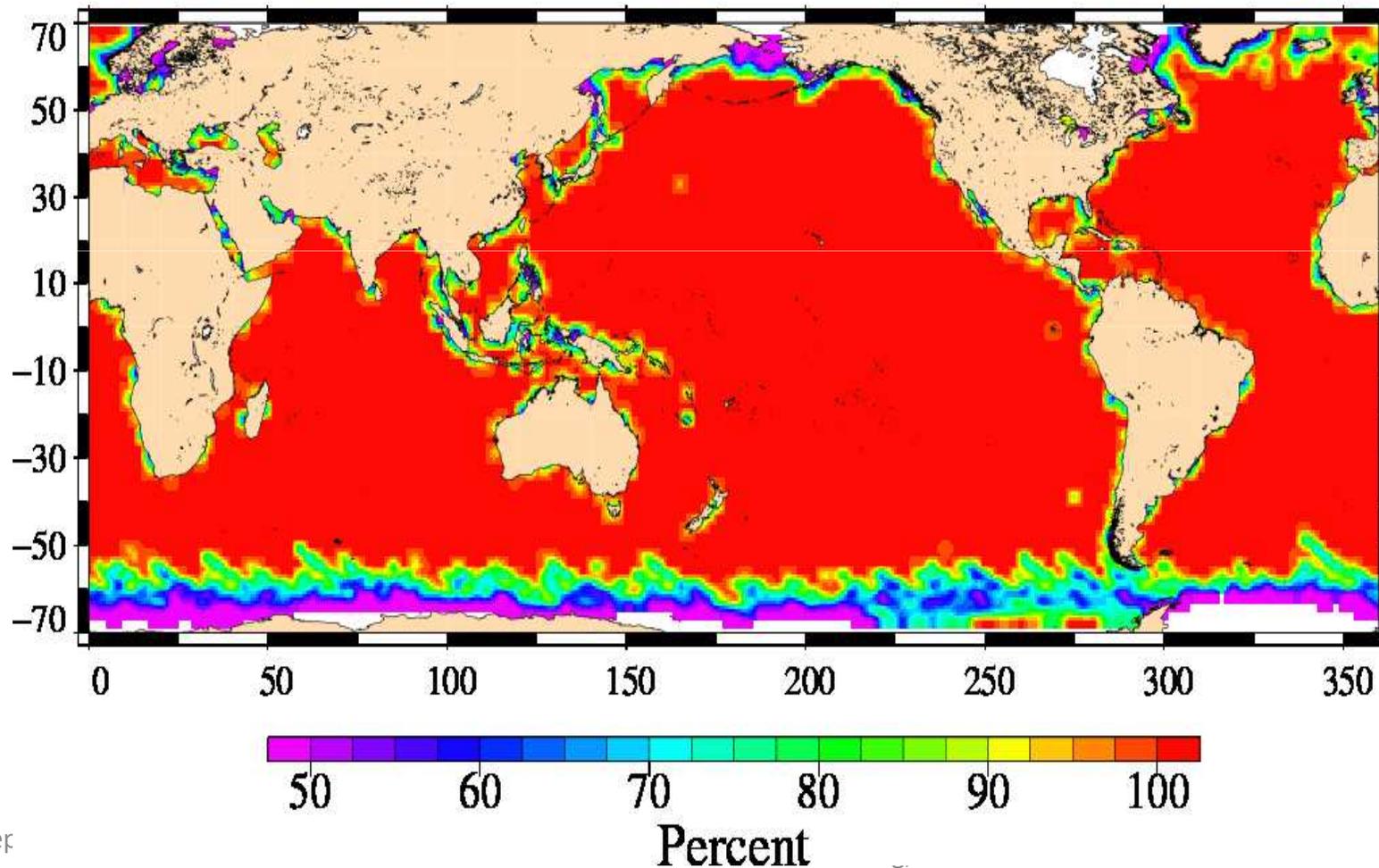
Variance of  
(OA – JMR)



# Percentage of computed OA wet tropo

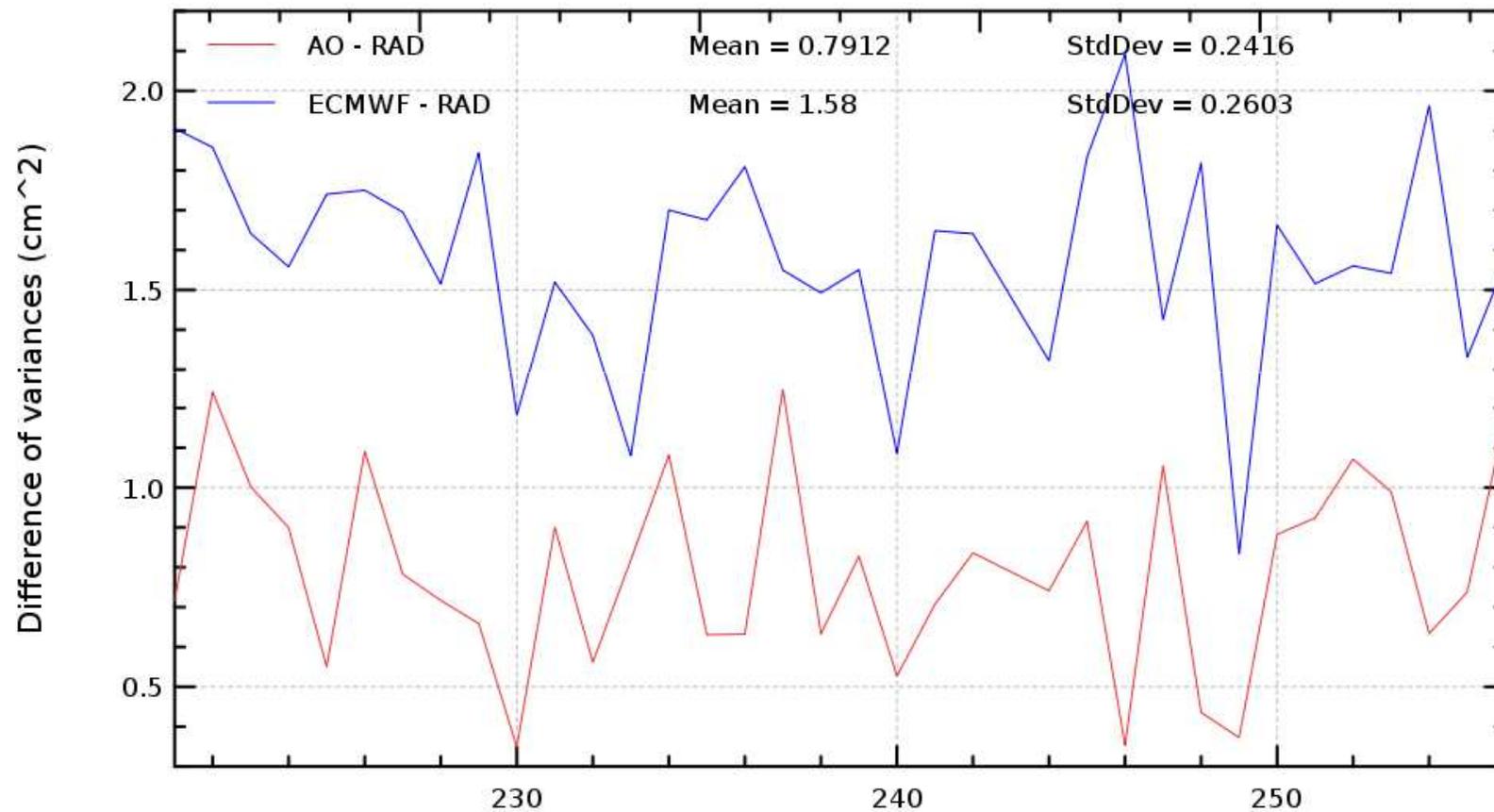
Percent of valid measures ( $ERR\_TRO\_HUM\_OA < 0.99$ )

Mission j1, cycle 234



# SSH Crossover statistics

$\text{VAR}(\text{SSH\_OA}) - \text{VAR}(\text{SSH\_RAD})$  &  $\text{VAR}(\text{SSH\_ECMWF}) - \text{VAR}(\text{SSH\_RAD})$



## Application to NRT

- Goal : to check the robustness of the method
- Applicability of the method to NRT Jason-2 IGDR production
- 11 sensors available in NRT in 2012 :
  - 6 AMSU-A (from NOAA CLASS) :
    - NOAA-15, NOAA-16, NOAA-17, NOAA-18, METOP-A, NOAA-19
  - AMSU-A on board AQUA (from GES DISC)
  - 1 SSMI and 2 SSMI/S (from RSS) :
    - F15, F16, F17
  - TMI (from GSFC for NRT availability)

## Application to NRT

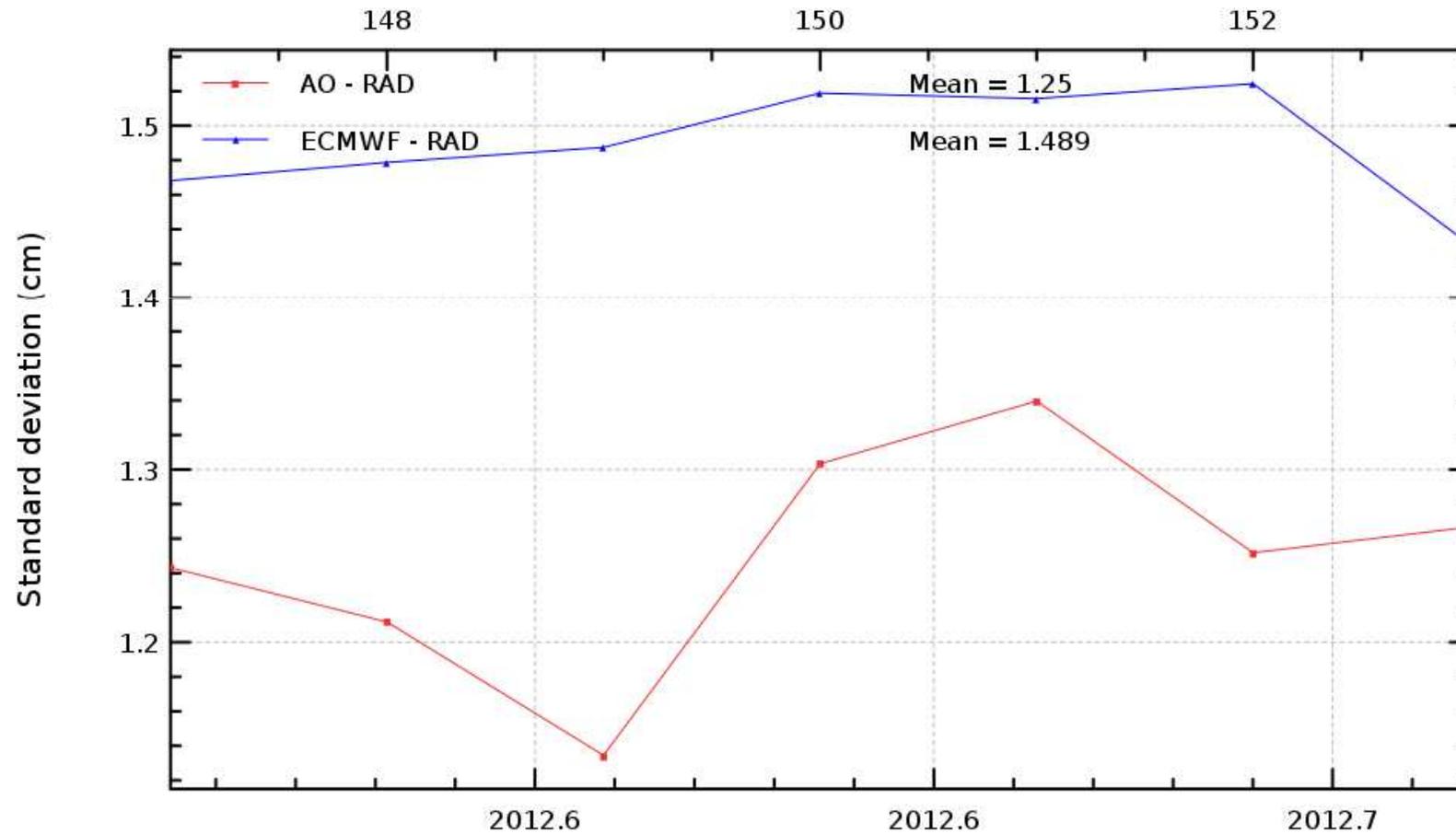
- Automatic processing run from July 1st, 2012
- 6-month duration (end 2012)
- Data acquisition from providers every 3 hours starting at 5h (Sea ice conc. needed first)
- OA run every day D at 12h on altimeter tracks of day D-2
- Uses sensor data from D-3 18h to D-1 06h :
  - All sensors available excepted : AMSU/Aqua and TMI GSFC data missing for D-1

## Application to NRT

- Automatic data validation procedures run :
  - Every day to check the data availability and plot the OA, ECMWF and AMR wet tropo corrections
  - Every 2 months for more in-depth evaluation
- To be done :
  - Recharacterization of sensor bias and noise relative to Jason-2 AMR (as soon as enough matchups available)

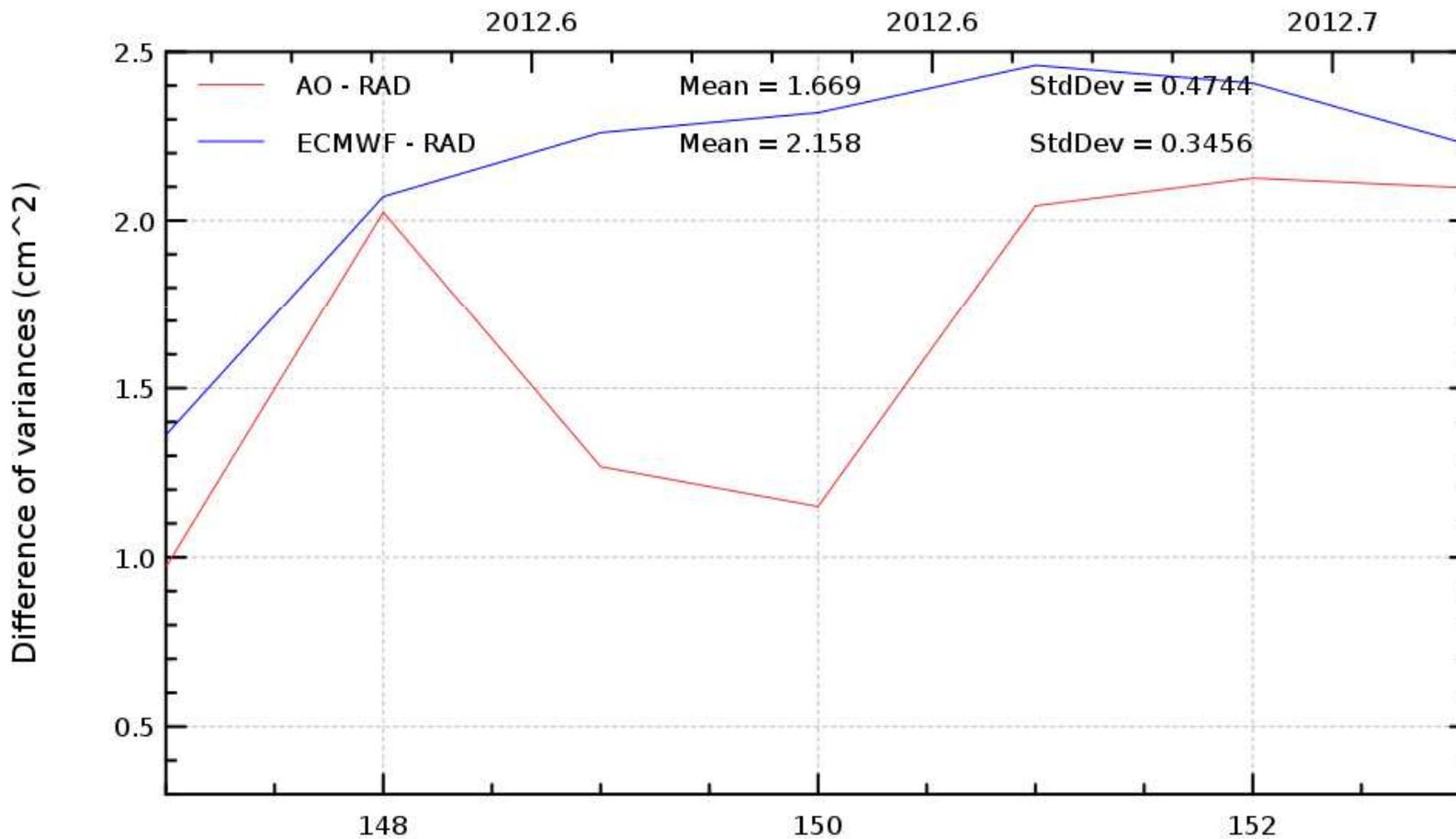
# Along-track statistics

Standard deviation of AO - RAD and ECMWF - RAD  
Mission j2, cycles 147 to 153



# Crossover SSH statistics

VAR(SSH with AO) - VAR(SSH with RAD) and VAR(SSH with ECMWF) - VAR(SSH with RAD)  
Mission j2, cycles 147 to 153



# Conclusions

- The calculation of the wet tropo correction by OA of ancillary radiometers has been improved.
- The JMR correction remains the best one for Jason-1. but the new OA correction performs significantly better than the ECMWF one.
- Application to NRT is underway (Jason-2), first results demonstrate the feasibility and robustness of the method (linked to sensor products availability).

We are ready to serve Cryosat-2 mission !