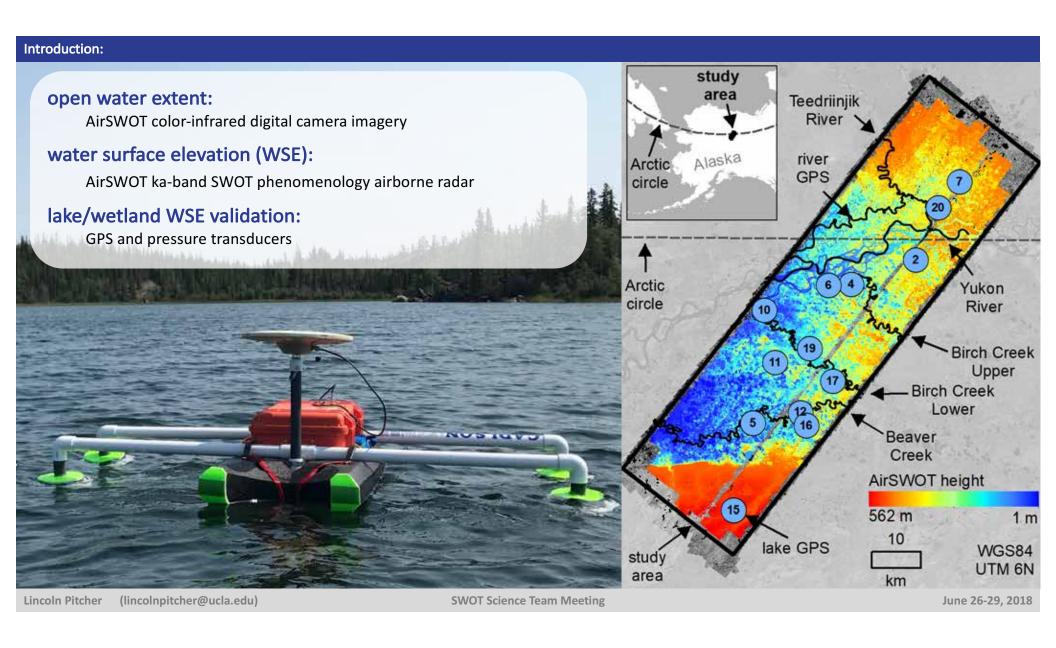


SWOT Science Team Meeting Lincoln Pitcher (lincolnpitcher@ucla.edu) June 26-29, 2018



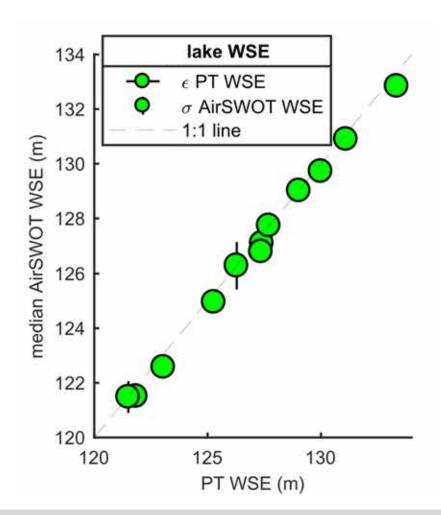
(1) can AirSWOT resolve WSE in lakes and wetlands with accuracies sufficient to validate SWOT?

SWOT mission accuracy standards: WSE in open water to ±10 cm per 1 km² and ±25 cm per 0.0625 km²

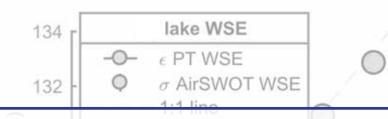
- (2) how might AirSWOT be used to enhance hydrologic understanding of Arctic and Boreal lake-river-wetland systems like the Yukon Flats?
- (3) AirSWOT updates

motivations: intended use of AirSWOT to validate SWOT, and AirSWOT as standalone instrument for surface water hydrology investigations

(1) can AirSWOT resolve WSEs in lakes and wetlands with accuracies sufficient to validate SWOT?



(1) can AirSWOT resolve WSEs in lakes and wetlands with accuracies sufficient to validate SWOT?



AirSWOT resolves lake WSE with overall RMSE 21 cm

2 of 5 lakes meet SWOT mission requirement for lakes >1km²

O of 3 lakes meet SWOT mission requirement for lakes 0.0625 to 1 km²

2 of 5 lakes <0.0625 km² WSE accuracies ±25 cm



AirSWOT remains experimental, research into sensor calibrations and improvements to processor are ongoing

from an airborne remote sensing perspective, these accuracies remain high, especially considering no additional ground calibrations

water surface roughness during data collection remains unknown

advances in data processing may increase accuracies in future

2015 data being reprocessed to mirror 2017 NASA ABoVE data

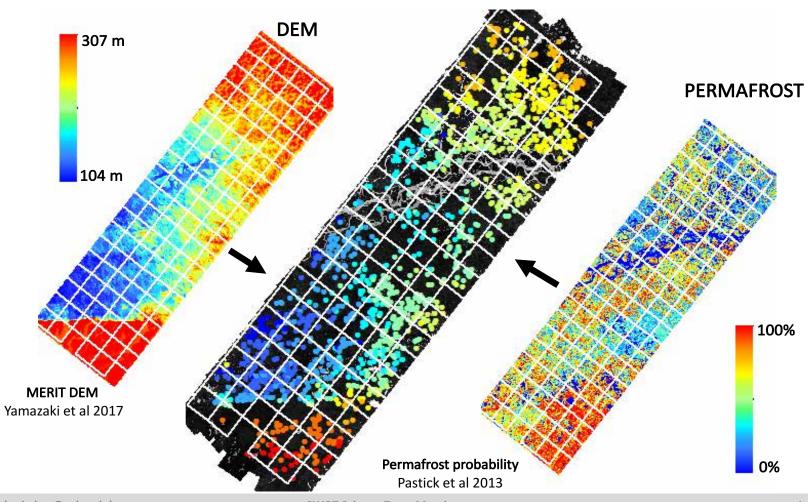
PT WSE (m)

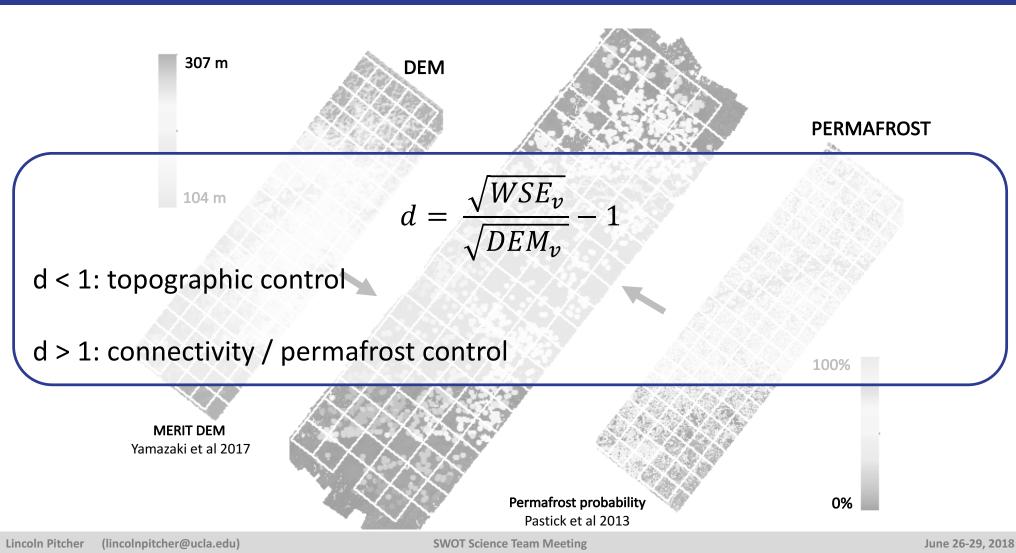
Lincoln Pitcher (lincolnpitcher@ucla.edu) SWOT Science Team Meeting June 26-29, 2018

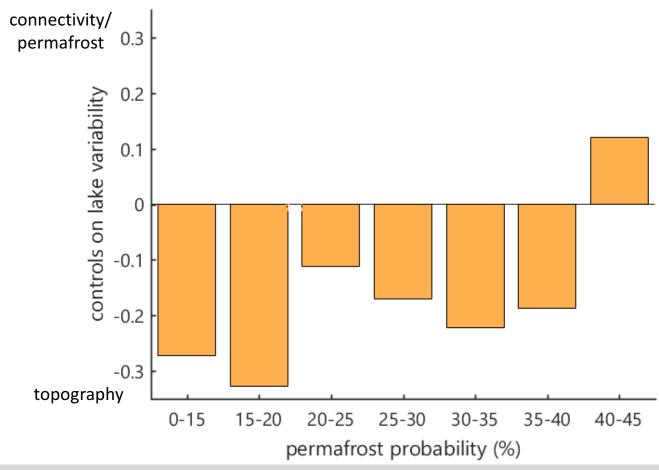
n = 1439 lakes

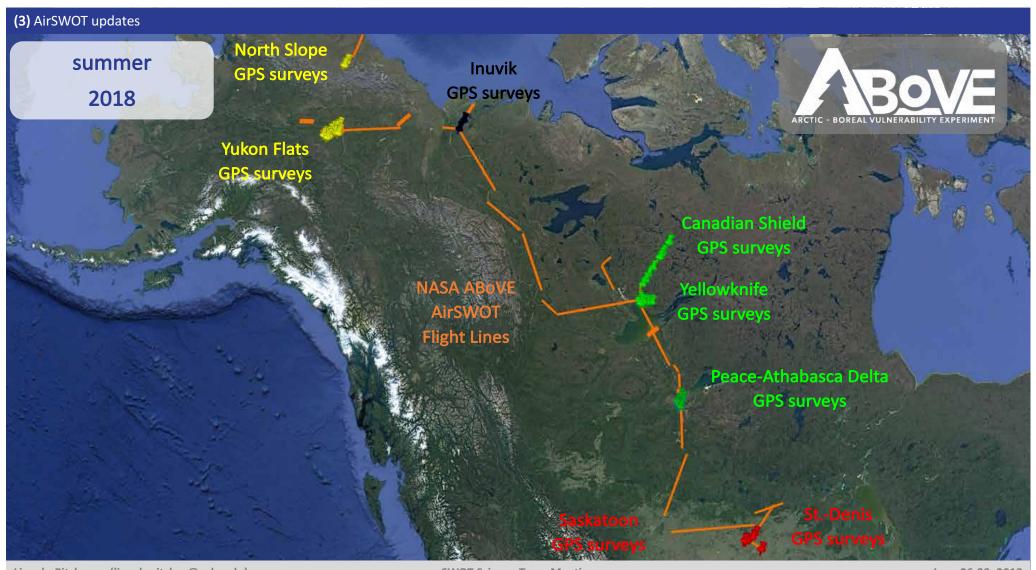
Lincoln Pitcher (lincolnpitcher@ucla.edu) SWOT Science Team Meeting June 26-29, 2018

n = 1439 lakes









(3) AirSWOT updates

- >28,000 km flown
- >40,000 Landsat observable water bodies (from Pekel et al 2016)
- >3,000 km² surface water area mapped (from Pekel et al 2016)
- >100 field validation GPS surveys in lakes across Canada and Alaska
- international collaborative field effort with participants from 15 institution across 4 countries































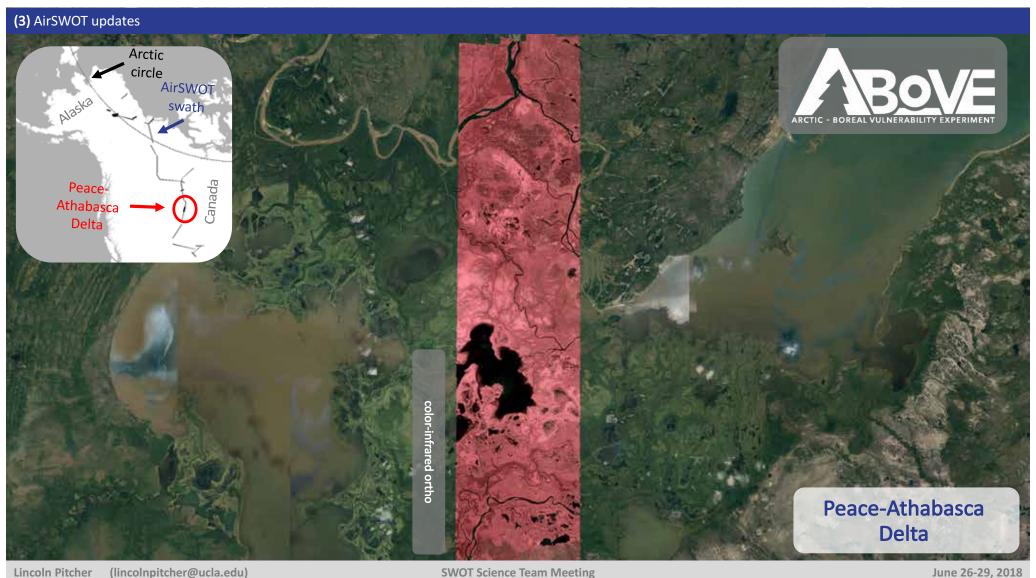




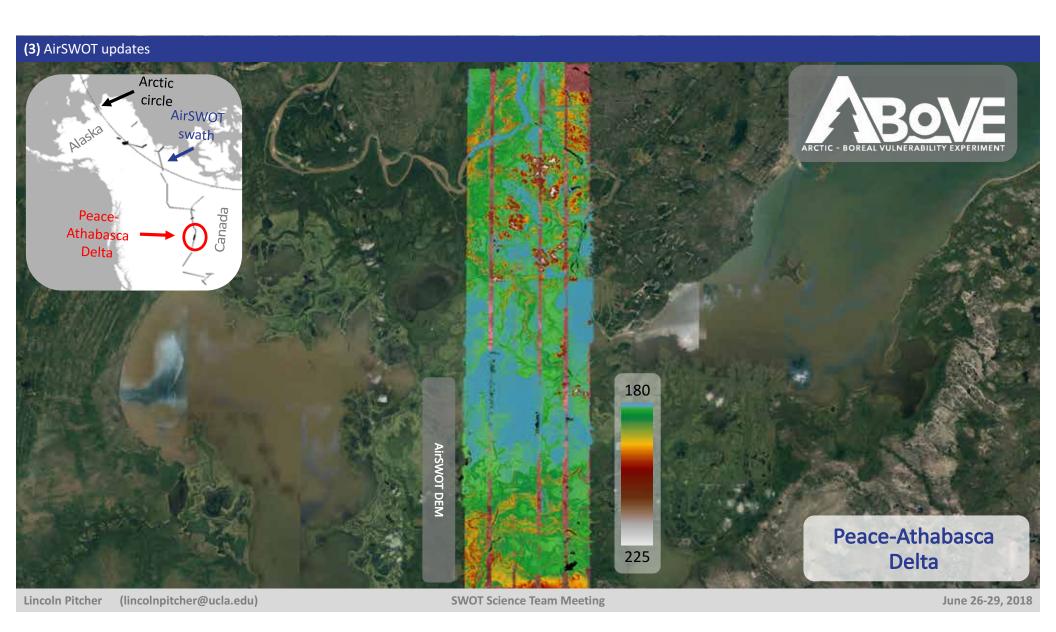


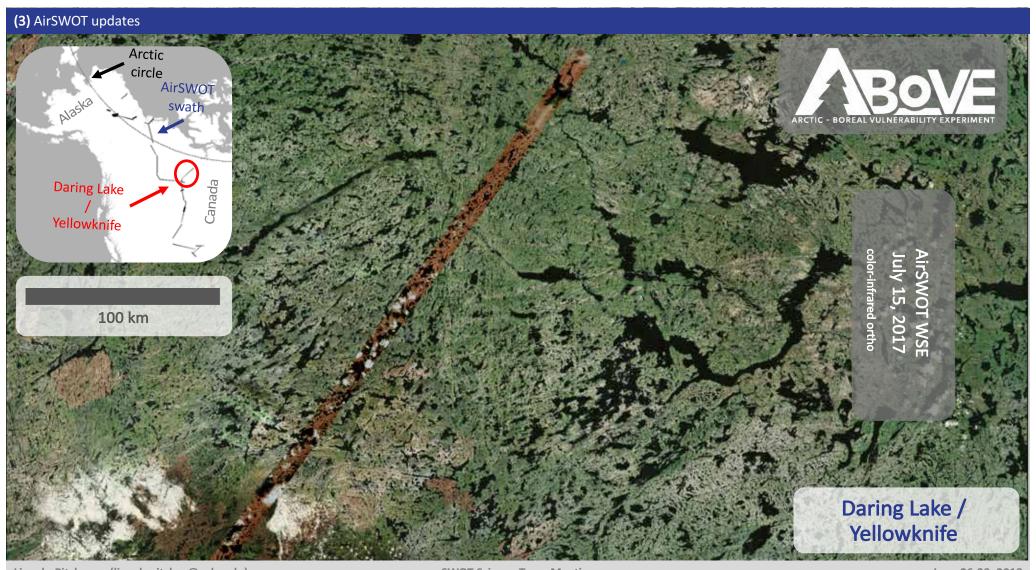


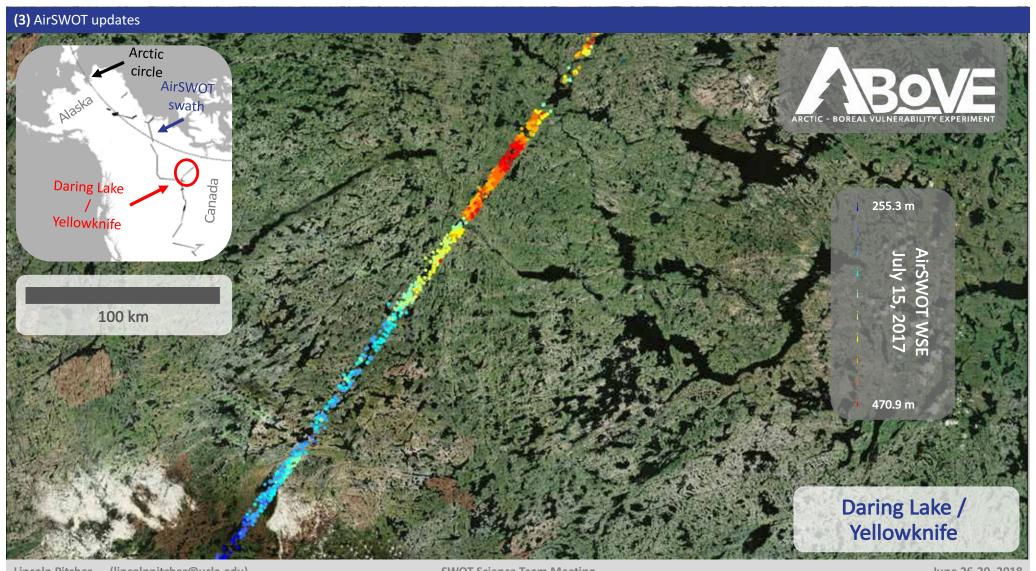




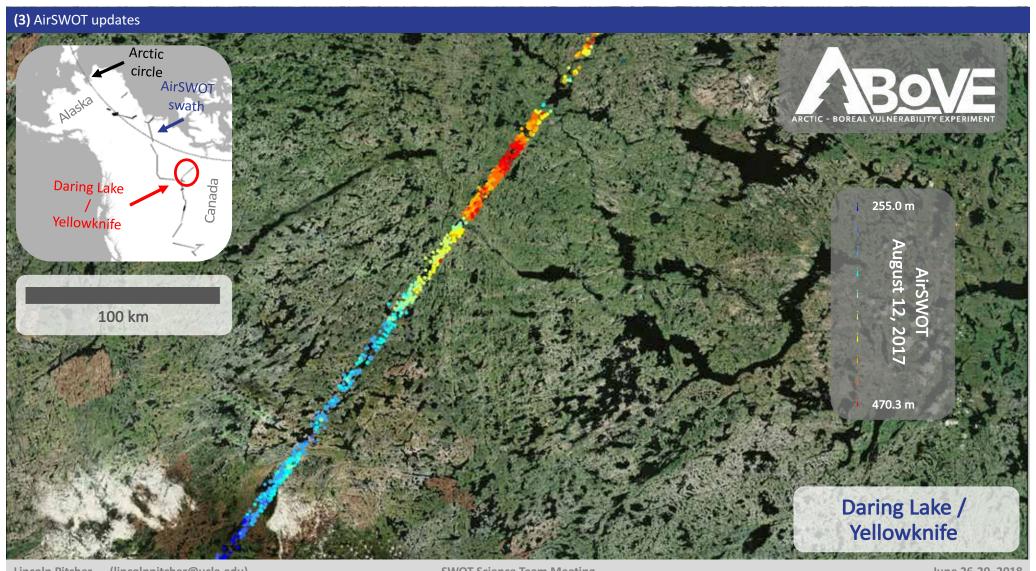
(lincolnpitcher@ucla.edu) **SWOT Science Team Meeting** June 26-29, 2018







June 26-29, 2018 Lincoln Pitcher (lincolnpitcher@ucla.edu) **SWOT Science Team Meeting**



June 26-29, 2018 Lincoln Pitcher (lincolnpitcher@ucla.edu) **SWOT Science Team Meeting**



June 26-29, 2018 Lincoln Pitcher (lincolnpitcher@ucla.edu) **SWOT Science Team Meeting**

Summary:

- (1) can AirSWOT resolve WSEs in lakes and rivers with accuracies sufficient to validate SWOT? AirSWOT lake and wetland WSEs from 2015 Yukon Flats data remains subpar for SWOT validation. However, wider range in environmental conditions (e.g. wind), refined calibrations and improvements to AirSWOT processor may improve accuracies in the future.
- (2) how might AirSWOT be used to enhance hydrologic understanding of complex lake-river-wetland systems we demonstrate AirSWOT's utility for mapping hydraulic gradients and assessing controls on lake levels across complex Arctic and Boreal wetland systems

(3) AirSWOT updates

AirSWOT was deployed as part of the **2017 NASA ABOVE** campaign. JPL is processing the data and it is also being prepared for submission to ORNL DAAC. Preliminary results suggest surface **water fluxes** can be estimated from repeat mappings. Future work includes: generating open water mask for AirSWOT radar extractions and refinement of AirSWOT lake/wetland WSE accuracy characteristics with field WSE surveys.



Acknowledgements:



This work was supported by:

NASA Terrestrial Hydrology Program grant: NNX13AD05G, managed by Dr. Jared Entin NASA Terrestrial Ecology Program grant: NNX17AC60A, managed by Dr. Hank Margolis NASA Earth and Space Sciences Fellowship Program grant: NNX14AP57H



AirSWOT radar data was processed by Albert Chen, Curtis Chen, and Craig Stringham at JPL custom engineered GPS equipment used for field surveys was designed and engineered by Dr. Alberto Behar at JPL



we would like to recognize the contributions of: Jean-Froncois Cretaux and Muriel Bergé-Nguyen at Centre National d'Etudes Spatiales (CNES) for completing the GNSS differential GPS processing



Professor Yongwei Sheng and Linghon Ke for assistance with layover simulations; Ariana Nickmeyer and Lin Lu for support with preliminary AirSWOT data analysis and water mask delineation



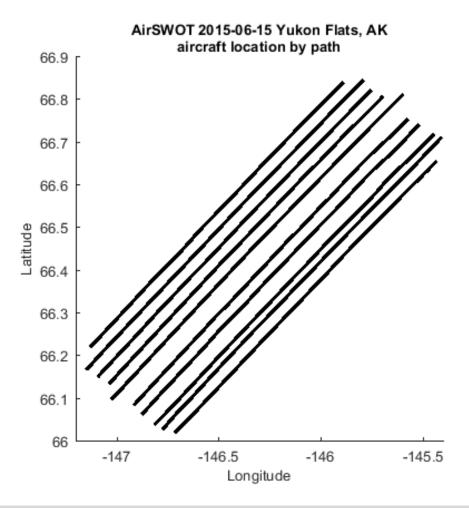
We would like to thank the Yukon Flats National Wildlife Refuge office, namely: Joshua Rose (aquatic ecologist), Mike Spindle (pilot), and Mike Hinkes (pilot).



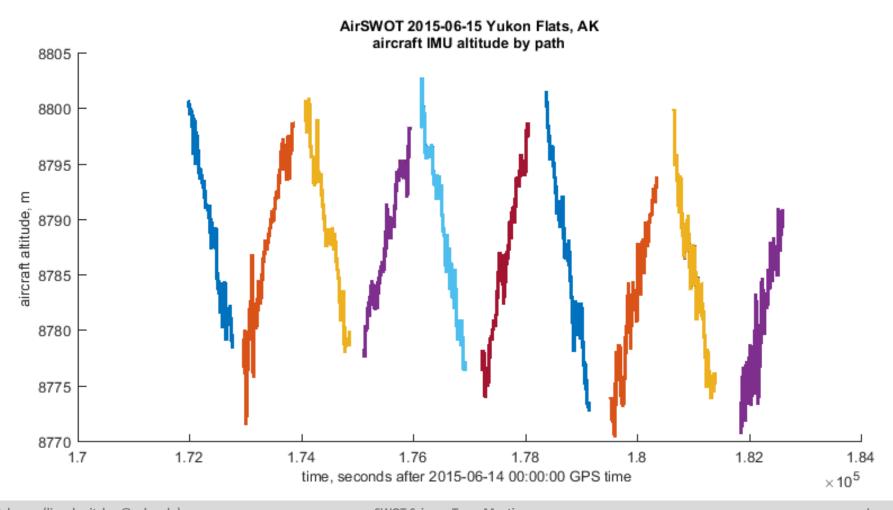
John Arveson of Cirrus Digital Systems for assistance with color-infrared digital imagery; Alex Shapiro of Alaska Land Exploration LLC for logistical and helicopter support

Jerry Carrol in Fort Yukon for transportation on the Yukon River.

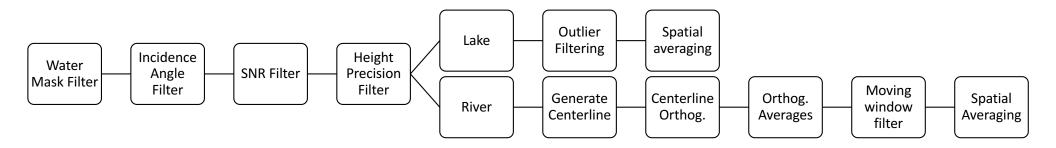
The Arctic DEM was created by the Polar Geospatial Center from DigitalGlobe, Inc., imagery and funded under National Science Foundation awards 1043681, 1559691, and 1542736.



Extra Slides:

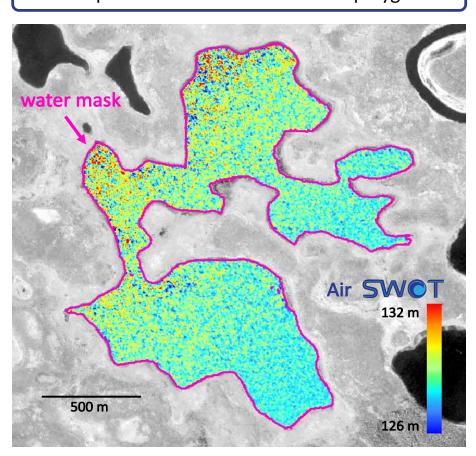


Extra Slides:

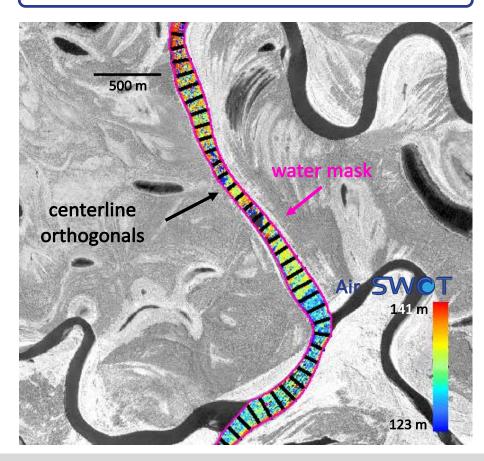


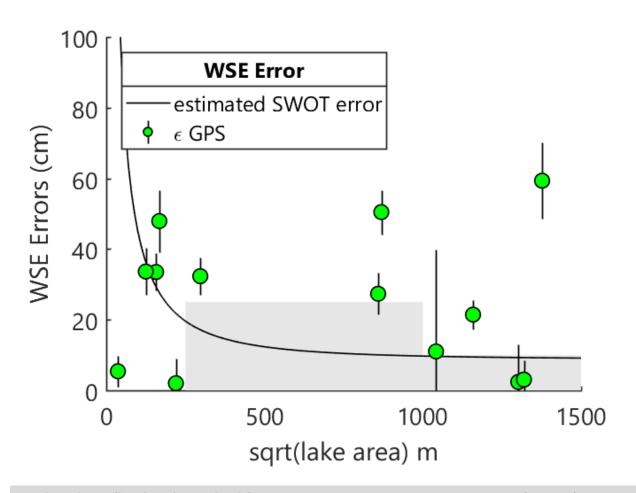
Extra Slides:

lakes processed within water mask polygons



rivers processed orthogonal to flow direction





YUKON FLATS LAKES:

SWOT requirement 2.8.3:

> 1km2

2 of 5 lakes ± 10 cm

0.0625 to 1km2

0 of 3 lakes ± 25 cm

no SWOT requirement:

< 0.0625 km2

2 of 5 lakes ± 25 cm

Lincoln Pitcher (lincolnpitcher@ucla.edu) AGU 2017 (H44H-01) Thursday December 14, 2017

